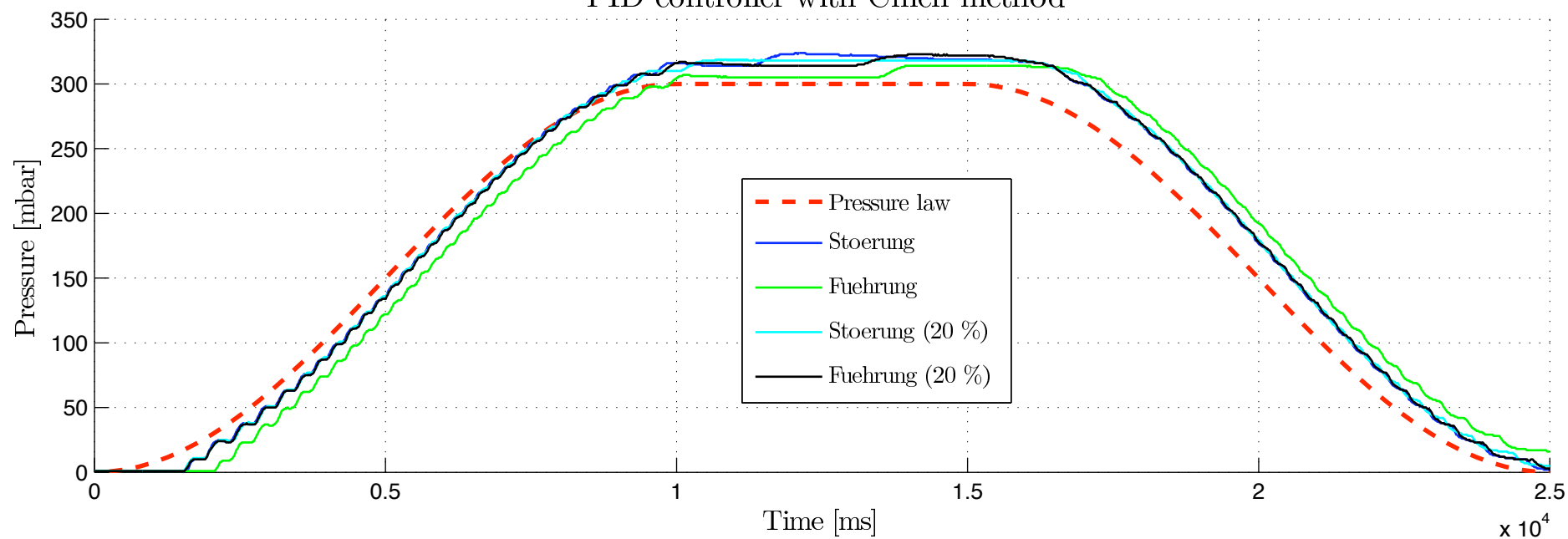
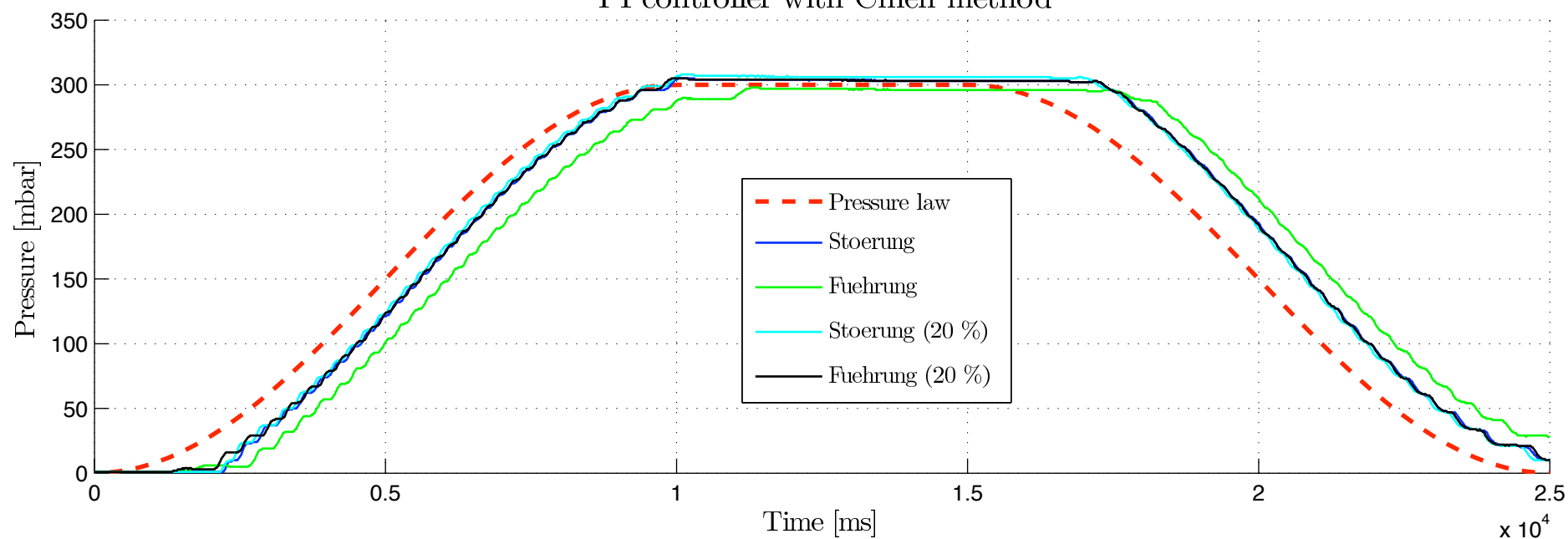


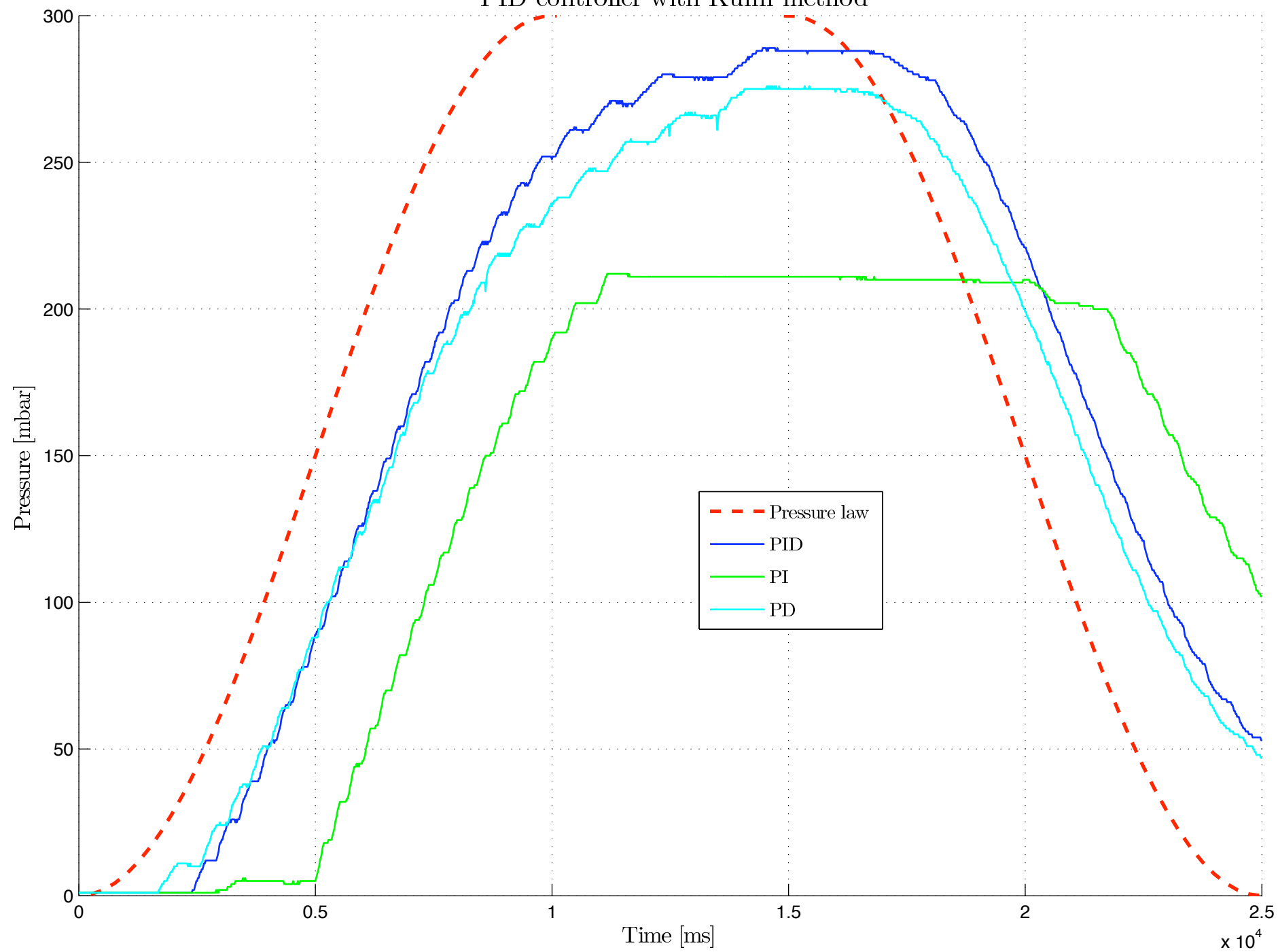
PID controller with Chien method



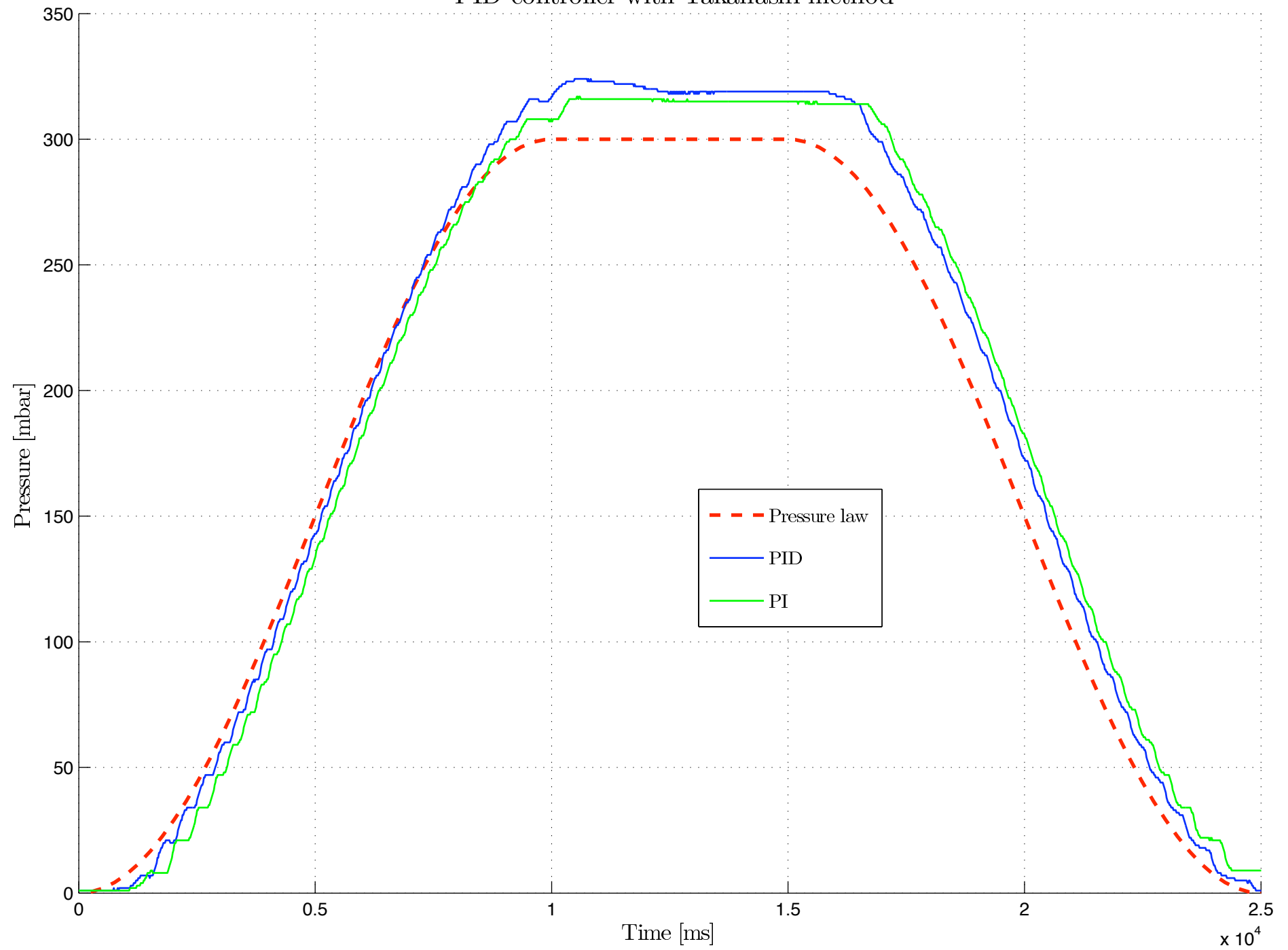
PI controller with Chien method



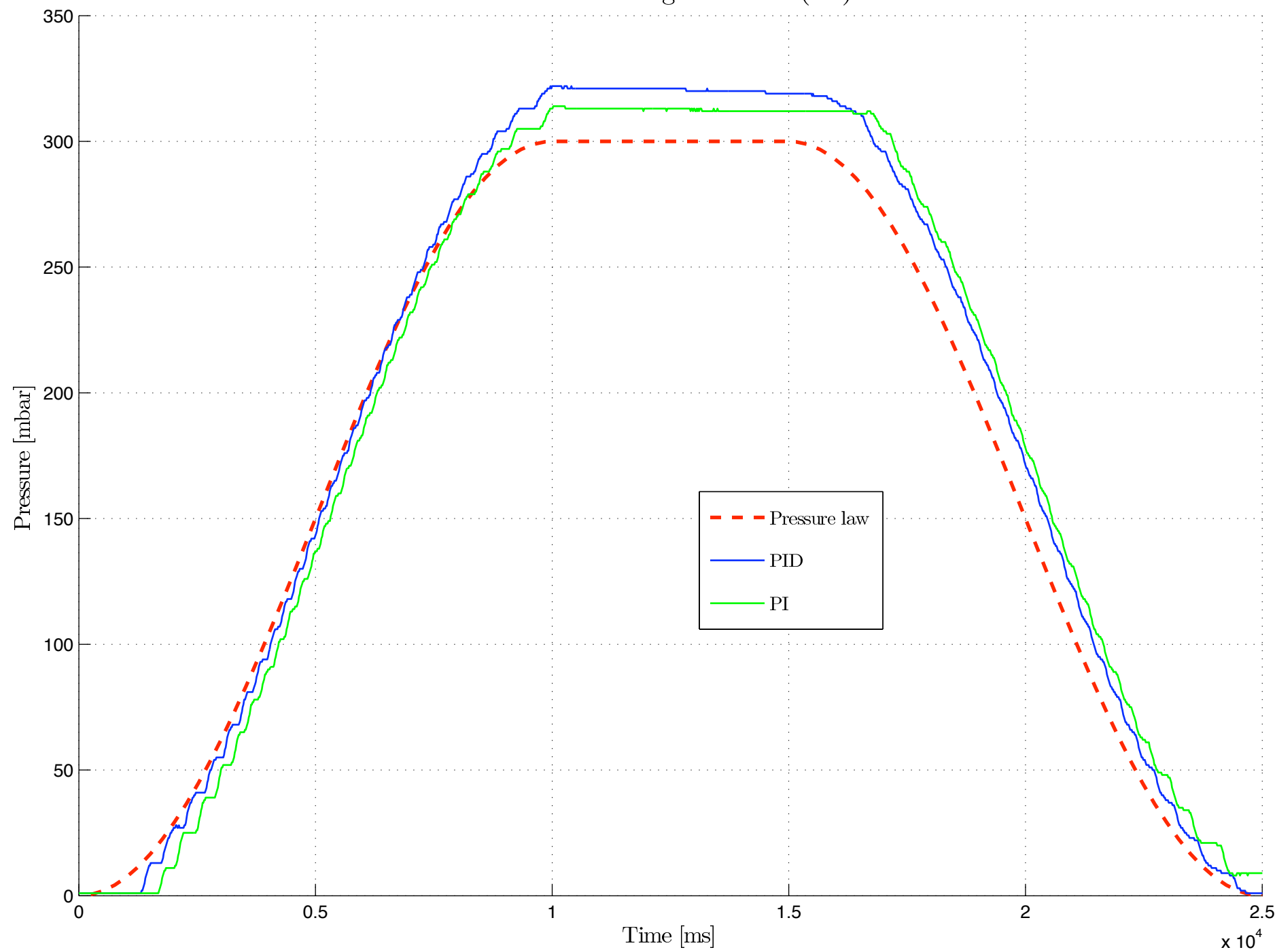
PID controller with Kuhn method



PID controller with Takahashi method



PID controller with Ziegler-Nichols (1st) method



PID controller with Ziegler-Nichols (2nd) method

