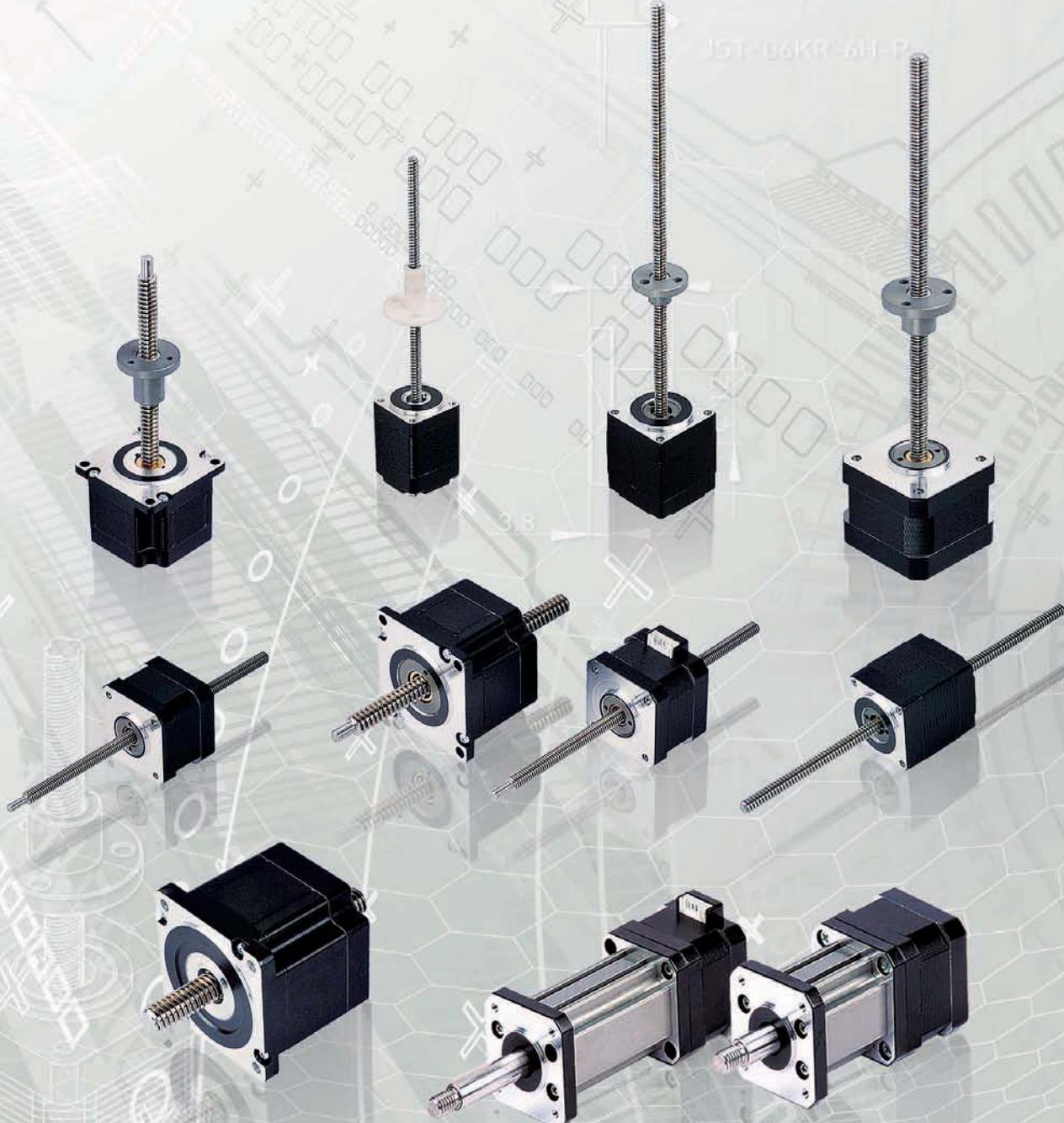


# DINGS'

Chang Zhou DINGS' Electrical & Mechanical Co., Ltd

## Precision Hybrid Stepper Linear Actuators



Quality · Performance · Flexibility · Price



## WHO IS DINGS'?

DINGS' is a premier supplier of Linear Motion Systems. Based in the greater Shanghai, China area, we manufacture quality lead screw and step motor systems used to solve motion applications in industries from medical, lab automation, packaging, electronic assembly, and other special machines throughout the world.



Shanghai Skyline

Our value proposition is a **QUALITY** product at very **COMPETITIVE PRICING**.

We have company representation in the United States, Canada and Europe.

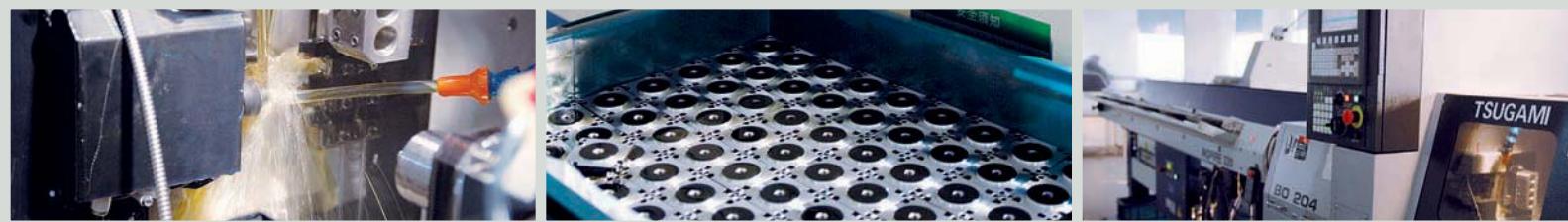
Please view our website at  
**[www.dingsmotion.com](http://www.dingsmotion.com)**

for the latest information on new products.

Contact our local Distributor and the Technical Support as noted on the back of this catalog.



Hybrid Stepper Motor Linear Actuators



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## TECHNOLOGY OVERVIEW

One of the most common methods of moving a load from point A to point B is through linear translation of a motor by a mechanical lead screw and nut. This section is here to assist and refresh your understanding of the basic principles of lead screw technology prior to selecting the system that is best for your application. Please also utilize the reference glossary at the end of the catalog to support your understanding as well.

Some basic design considerations are as follows:

1. What is the load of your system?
2. What is the required speed to go from point A to point B?
3. What is the distance you need to travel?
4. What is the required time to move from point A to point B?
5. What accuracy does your application require?
6. What repeatability does your application require?
7. Horizontal vs vertical orientation?

## An Explanation of the Basics

### LEADS VS PITCH

Pitch is the axial distance between threads. Pitch is equal to lead in a single start screw. There may be more than one thread „strand“ on a single screw. These are called starts. Multiple start lead screws are usually more stable and efficient at power transmission.

Lead is the axial distance the nut advances on one revolution of the screw. Throughout this catalog, lead will be the term used for specifying a screw as it is the linear distance travelled for one revolution of the screw. The larger the lead, the more linear distance travelled per one revolution of the screw.

### LOAD

Typically quantified as either lbs OR kg to move or pounds force (lbsF) or kgF for thrust.

### VELOCITY (V)

Typically quantified as either inches/second (mm/sec) required for your application.

### DISTANCE

Typically quantified as either inches or mm, is the required move distance.

### TIME (t)

Typically quantified in seconds. Time period required for a given distance defines the velocity, acceleration (A), and deceleration needed to reach commanded position.

## HORIZONTAL OR VERTICAL APPLICATION

Vertical orientation applications add the potential problem of backdriving when power to the motor is off and without an installed brake. Vertical applications also have an additional gravity factor that must be part of the load/force calculation.

## ACCURACY OF SCREW

Specified as a measurement over a given length of the screw. For example: 0.0006 in per inch. Lead accuracy is the difference between the actual distance travelled versus the theoretical distance travelled based on the lead. For example: A screw with a 0.5 inch lead and 0.004 inch per foot lead accuracy rotated 24 times theoretically moves the nut 12 inches.

However, with a lead accuracy of 0.004 inch per foot, actual travel could be from 11.996 to 12.004 inches.

## TOTAL INDICATED RUNOUT

The amount of „wobble” around the centerline of the screw.

## REPEATABILITY

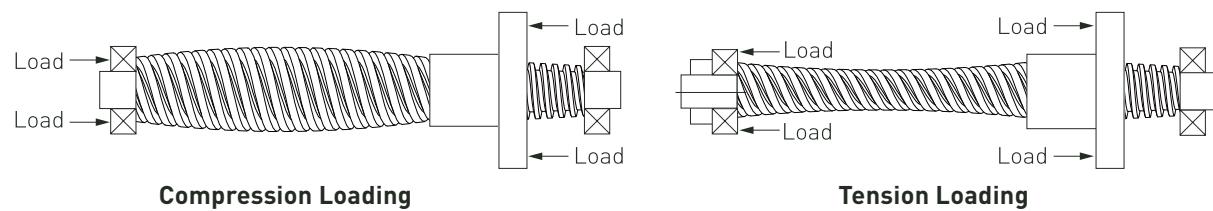
Most motion applications put the most significance on the repeatability (vs accuracy of screw) of a system to reach the same commanded position over and over again. For example: A repeatability of  $\pm .005$  inch means that after repeated commands to reach the same target position, the linear error will be no more than  $\pm .005$  inch.

## TENSION OR COMPRESSION LOADING

A load that tends to stretch the screw is called a tension load.

A load that tends to „squeeze” or compress the screw is called a compression load.

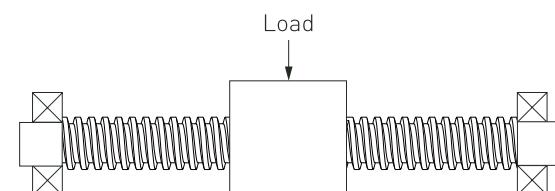
Depending on the size of the load, designing the screw in tension utilizes the axial strength of the screw versus column loading.



## RADIAL LOAD

A load perpendicular to the screw.

This is not recommended unless additional mechanical support such as a linear guide is used.

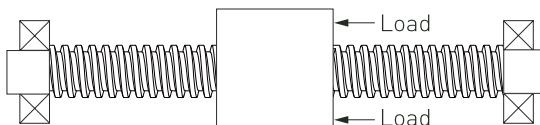


## Radial Loading

(Avoid or Minimize)

## AXIAL LOAD

A load that is exerted at the center line of the lead screw.



### Axial Center Loading

(best)

## STATIC LOAD

The maximum thrust load, including shock load, that should be applied to a non-moving screw.

## DYNAMIC LOAD

The maximum recommended thrust load which should be applied to the screw while in motion.

## BACKDRIVING

Backdriving is the result of the load pushing axially on the screw or nut to create rotary motion. Generally, a nut with an efficiency greater than 50% will have a tendency to backdrive. Selecting a lead screw with an efficiency below 35% may prevent backdriving. The smaller the lead, the less chance for backdriving or free wheeling. Vertical application are more prone to backdriving due to gravity.

## TORQUE

The required motor torque to drive just the lead screw assembly is the total of:

1. Inertial Torque
2. Drag Torque
3. Torque to move load

Drag Torque = Friction of the nut and screw in motion

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## LUBRICATION

The nut material contains a self-lubricating material that eliminates the need for adding a lubricant to the system. The Teflon coated screw option also lowers friction and extends life of the system.

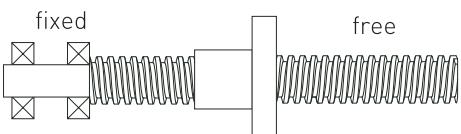
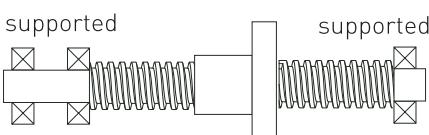
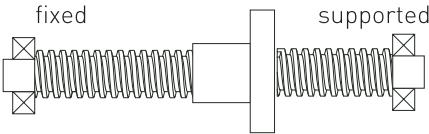
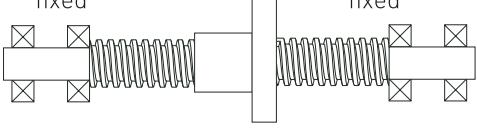
## END MACHINING OF THE SCREW

Standard metric or English options are available as well as custom requirements.

	Threaded end	Metric end: M4 x 0.7 mm thread to within 0.03"/0.76 mm of shoulder	UNC end: # 8-32 UNC-2A thread to within 0.03"/0.76 mm of shoulder
	Smooth end		$\varnothing 0.1967" \pm 0.001$ $\varnothing 5 \text{ mm} \pm 0.025$
	None		—

## FIXITY

The performance (speed and efficiency) of the screw system is affected by how the screw ends are attached and supported.

Type of End Fixity	Relative Rigidity	Critical Speed Factor	Critical Load Factor
	Less Rigid	32	25
	Rigid	1.0	1.0
	More Rigid	1.55	2.0
	Most Rigid	2.24	4.0

## COLUMN STRENGTH

When a screw is loaded in compression its limit of elastic stability can be exceeded and the screw will fail through bending or buckling.

## CRITICAL SPEED

Critical speed is the rotational speed of the screw at which the first harmonic of resonance is reached due to deflection of the screw.

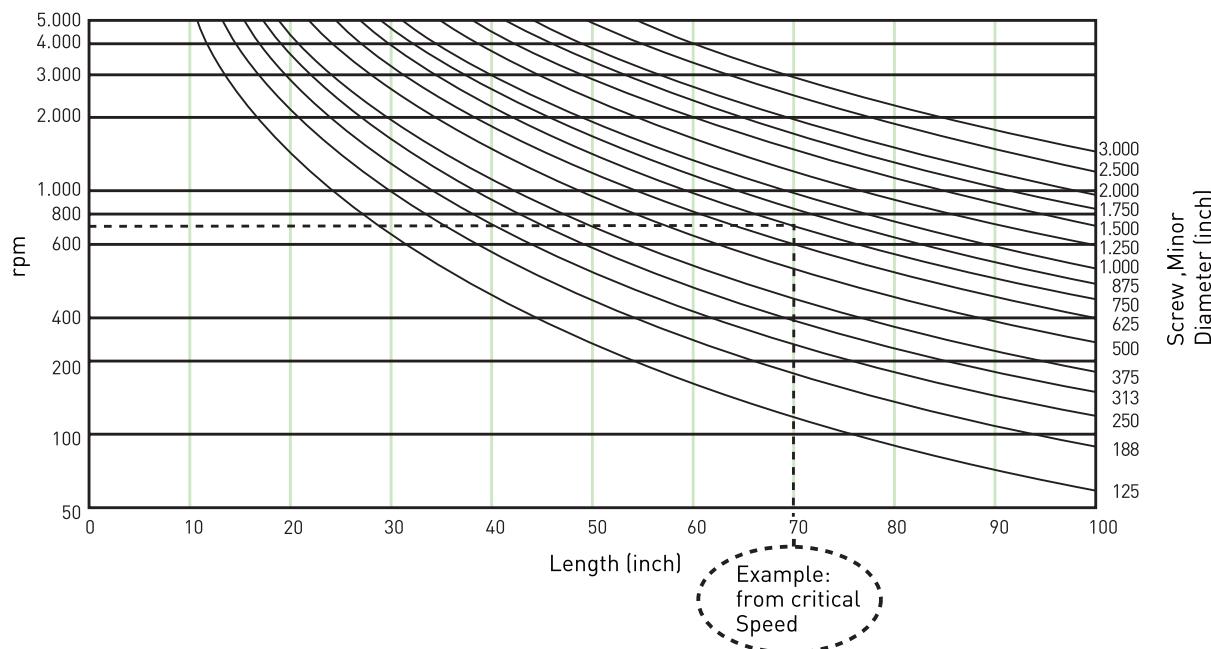
A system will vibrate and become unstable at these speeds.

Several variables affect the speed at which a system will reach critical speed:

1. The lead of the screw
2. The rotational speed
3. End fixity
4. The thrust load
5. Diameter of the screw
6. Tension or compression loading

For example the following chart shows that for a screw with a diameter of 3/4 inch and 70 inch length, the threshold for critical speed is 700 RPM.

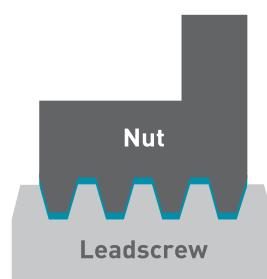
**CRITICAL ROTATION SPEED (RPM) VS. UNSUPPORTED SCREW LENGTH FOR VARIOUS SCREW DIAMETERS (INCH)**



**BACKLASH**

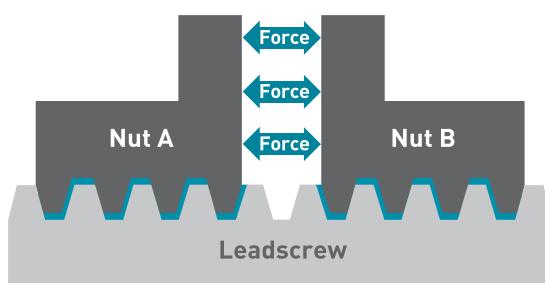
Backlash is the relative axial movement between a screw and nut at standstill. It is normal for backlash to increase with wear over time. Backlash compensation or correction can be accomplished through the application of an anti-backlash nut. Backlash is usually only a concern with bi-directional positioning.

**Standard Nut**



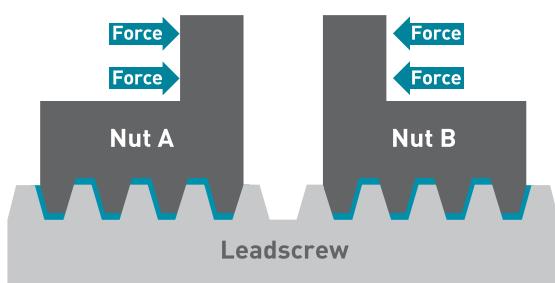
**BACKLASH IN BLUE**

**Tension Anti-Back Lash Nut**



**BACKLASH IN BLUE**

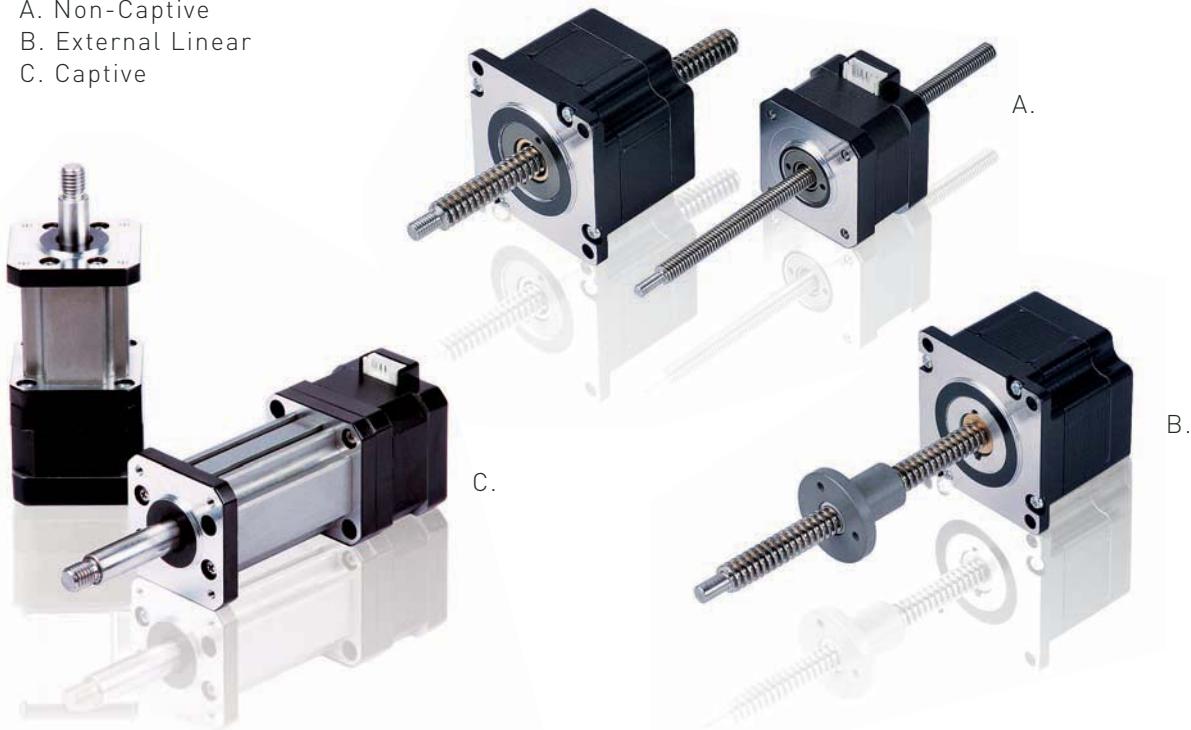
**Compression Anti-Back Lash Nut**



**BACKLASH IN BLUE**

**LINEAR MOTION SYSTEM TYPES**

- A. Non-Captive
- B. External Linear
- C. Captive

**WHY CHOOSE ONE FORM FACTOR OVER THE OTHER?**

1. What is the best mechanical fit for your application?
2. How do you plan to attach the screw?
3. Is rotation of the screw acceptable?
4. Does your application require an encoder or brake?
5. What is the stroke of your application?

**WHAT ENVIRONMENTAL CONSIDERATIONS DO YOU HAVE?**

DINGS' linear motion systems are designed to operate in dry and non-corrosive environments. The standard product does not have an IP rating. Operating the linear systems in dirty or corrosive environments will significantly reduce product life.

**TEMPERATURE**

Very high or low temperatures may cause significant changes in the nut fit or drag torque.

**MAXIMUM DYNAMIC LOAD**

Each Nema frame size motor has a mechanical load maximum that should not be exceeded. See Speed/Torque curves for the individual frame sizes.

**MOTOR SELECTION**

In order to select the right motor combination with the lead screw several factors should be considered:

1. How much torque is required?
2. What is the desired step angle?
3. Detent or holding torque requirements?
4. Physical size restrictions?
5. What type of driver (amplifier) are you using?

## Basic Specifications of DINGS' Linear Systems

### LEAD SCREW MATERIAL

Unless otherwise noted, all reference to lead screws in this catalog have the following characteristics:

**Lead screw material** 303 Stainless precision cold rolled steel

**Screw Coating** Teflon coating is optional

**DINGS' linear actuator screws are manufactured by a precision rolling process**

**Standard screw accuracy** 0.0006 in/inch  
**(Lead accuracy)**

**Screw repeatability** ± .006 inch

**System repeatability** (Motor and Screw) Nominally the same as screw repeatability, motor variance adds ± 6 micro steps.

**Screw straightness** .003 in/foot, measured as Total Indicated Runout (TIR)  
All screws are carefully checked for straightness before shipment.

**Screw Efficiency** From 35% to 85% dependent on lead  
Also depends on the usage of an anti-backlash nut with screw.  
The larger the lead, the higher the efficiency of the screw.

**Operating temperature** -10 °C to +50 °C

**Screw backlash** Depends on lead (nominally ± .005 in)

**System backlash** Includes screw, motor, and attached mechanics  
This will be the sum of all the backlash in your motion axis.

**Nut Material** Polyacetal with lubricating additive  
Standard is a free-wheeling nut.  
[Anti-backlash version is available]

**Wear life of screw and nut** Depends on load, speed, duty cycle, and environmental factors  
[typically > 5 million cycles]

**Note:** DINGS' linear systems are manufactured from high quality materials. Because of the variable effects of friction, lubrication, and cleanliness, an exact life cannot be predicted for a given application.

## Product Selection Considerations

There are many inter-related variables to consider when selecting the right linear motion system for your application. Your load and speed requirements will determine other variables such as the size of motor, the lead of the screw and ultimately the voltage and current requirements of your electronic motor driver. Depending on your application, tradeoffs can be made with many variables as you finalize the system that will meet your performance, form factor, and cost specifications.

### SELECTION

Quantify these basic variables first:

1. Load that you need to move (or push – Thrust)
2. Velocity
3. Distance to travel (Stroke)
4. Time required to move from point A to point B (Acceleration required)
5. Torque requirements of your entire system
6. How much backlash is acceptable in your system?
7. What is the required positional repeatability?
8. Is this a Vertical or Horizontal orientation?

Using the PRODUCT SELECTION SYSTEM along with the follow charts and linear motor sections, you can select your specific part number.

## WARRANTY

### Twenty Four month limited warranty

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<b>FIRST YEAR</b>	Full Replacement
<b>SECOND YEAR</b>	Parts Replacement

Seller warrants its products delivered hereunder to conform to stated specifications and to be free from defects in materials and workmanship. This warranty shall not apply to any product which shall have been improperly installed or subjected to misuse or neglect or which has been repaired or altered except by seller's accredited representative, nor to any product which has been subjected to accident.

### DISCLAIMER:

The information in this catalog has been carefully checked and is believed to be accurate; however no responsibility is assumed for inaccuracies.

DINGS' reserves the right to make changes without further notice to any products herein to improve reliability, function, or design.

DINGS' does not recommend the use of its products in life support or aircraft applications wherein a failure or malfunction of the product may directly threaten life or injury.

## Product Selection System

17 E 2 035 K 4-057-001

① ② ③ ④ ⑤ ⑥ ⑦ ⑧

### Options Defined

① Nema Motor Size:

Nema Code	8	11	14	17	23	34
Motor Size (mm)	20	28	35	42	57	86

② Leadscrew Shaft Style

N = Non-Captive Linear  
E = External Linear  
C = Captive Linear

③ Motor Step Angle

2 = 2-Phase with 1.8 degree step angle  
4 = 2-Phase with 0.9 degree step angle  
3 = 3-Phase with 1.2 degree step angle  
5 = 5-Phase with 0.72 degree step angle

④ Motor Length

Choice of single or double stack motor  
035 = 35 mm  
(See selection associated with each Nema size)

⑤ Motor internal leadscrew Lead Code (See Table)

- ⑥ Number of Lead Wires  
C4 = 4 position connector option  
C6 = 6 position connector option  
4 = Qty 4 Flying Leads  
6 = Qty 6 Flying Leads  
8 = Qty 8 Flying Leads

#### Note:

Nema 8 to Nema 17 motors have JST connector option.  
Nema 23 and Nema 34 motors have flying leads as only option.

⑦ Motor rated current per phase

057 = 0.57 Amps/phase  
(See selection associated with each Nema size)

⑧ Reserved for customer version (001 is default)

#### Lead Screw length

Non-Captive and External Linear – specify length of screw  
Captive version – specify stroke length  
(See sections on Nema 14, 17, and 23)

#### Note:

**Unless specified differently all screws are as follows:**

1. Right hand screw threads
2. Standard lubrication on leadscrew
3. No teflon coating

**Custom Leadscrew and Motor specifications welcome**

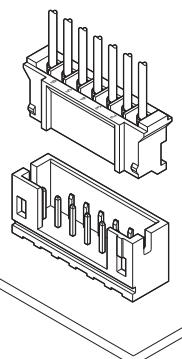
### END MACHINING OF THE SCREW

Standard metric or English options are available as well as custom requirements.

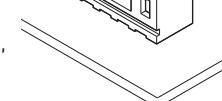
Threaded end	Metric end: M4 x 0.7 mm thread to within 0.03" / 0.76 mm of shoulder	UNC end: # 8-32 UNC-2A thread to within 0.03" / 0.76 mm of shoulder
Smooth end	$\varnothing 0.1967" \pm 0.001$ $\varnothing 5 \text{ mm} \pm 0.025$	
None	—	

**For volume OEM applications only.**

JST Connector  
Nema 8 and 11  
S6B-ZR-3.4  
Mating connector,  
ZHR-6



JST Connector  
Nema 14 and 17  
S6B-PH-K-S  
Mating connector,  
PHR-6



## Motor Lead Screw Code Schedule

Lead Code	Travel per Step mm (inch)	Size 8	Size 11	Size 14	Size 17	Size 23	Size 34
		Screw Dia. mm (inch)					
		3.5052 (0.128")	4.775 (0.188")	6.35 (0.25")	6.35 (0.25")	9.525 (0.375")	15.875 (0.625")
Screw Lead mm (inch)							
A	0.003175 (0.000125")		0.635 (0.025")			0.635 (0.025")	
B	0.006096 (0.00024")	1.2192 (0.048")		1.2192 (0.048")	1.2192 (0.048")		
D	0.00635 (0.00025")		1.27 (0.05")	1.27 (0.05")	1.27 (0.05")	1.27 (0.05")	
F	0.008 (0.000315")			1.6002 (0.063")	1.6002 (0.063")	1.6002 (0.063")	
G	0.01 (0.000395")	2.0 (0.079")					
H	0.010541 (0.000415")					2.1082 (0.083")	
J	0.012192 (0.00048")			2.4384 (0.096")	2.4384 (0.096")		
K	0.0127 (0.0005")		2.54 (0.1")	2.54 (0.1")	2.54 (0.1")	2.54 (0.1")	2.54 (0.1")
L	0.015875 (0.000625")					3.175 (0.125")	3.175 (0.125")
M	0.02 (0.00079")	4.0 (0.158")					
P	0.021209 (0.000835")					4.2418 (0.167")	
Q	0.024384 (0.00096")			4.8768 (0.192")	4.8768 (0.192")		
R	0.0254 (0.001")		5.08 (0.2")			5.08 (0.2")	5.08 (0.2")
S	0.03175 (0.00125")			6.35 (0.25")	6.35 (0.25")	6.35 (0.25")	6.35 (0.25")
T	0.04 (0.001575")	8.0 (0.315")					
U	0.042291 (0.001665")			8.382 (0.33")	8.382 (0.33")		
V	0.047625 (0.001875")					9.525 (0.375")	
W	0.048768 (0.00192")			9.7536 (0.384")	9.7536 (0.384")	9.7536 (0.384")	
X	0.0508 (0.002")		10.16 (0.4")				
Y	0.0635 (0.0025")			12.7 (0.5")	12.7 (0.5")	12.7 (0.5")	12.7 (0.5")
Z	0.127 (0.005")					25.4 (1.0")	25.4 (1.0")
AA	0.003048 (0.00012")	0.6096 (0.024")		0.6096 (0.024")	0.6096 (0.024")		

## Motor Size with available Lead Screw List

Motor Size	(mm)	Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Lead (mm)	Travel per Step (mm)*
Nema 8	20x20	0.138	3.5052	0.024	0.6096	0.003
Nema 8	20x20	0.138	3.5052	0.048	1.2192	0.0061
Nema 8	20x20	0.138	3.5052	0.079	2.0	0.01
Nema 8	20x20	0.138	3.5052	0.158	4.0	0.02
Nema 8	20x20	0.138	3.5052	0.315	8.0	0.04
Nema 11	28x28	0.188	4.7752	0.025	0.635	0.0031
Nema 11	28x28	0.188	4.7752	0.05	1.27	0.0063
Nema 11	28x28	0.188	4.7752	0.1	2.54	0.0127
Nema 11	28x28	0.188	4.7752	0.2	5.08	0.0254
Nema 11	28x28	0.188	4.7752	0.4	10.16	0.0508
Nema 14/17	35x35/42x42	0.25	6.35	0.024	0.6096	0.003
Nema 14/17	35x35/42x42	0.25	6.35	0.05	1.27	0.0064
Nema 14/17	35x35/42x42	0.25	6.35	0.063	1.6002	0.008
Nema 14/17	35x35/42x42	0.25	6.35	0.096	2.4384	0.0122
Nema 14/17	35x35/42x42	0.25	6.35	0.1	2.54	0.0127
Nema 14/17	35x35/42x42	0.25	6.35	0.192	4.8768	0.0244
Nema 14/17	35x35/42x42	0.25	6.35	0.25	6.35	0.0318
Nema 14/17	35x35/42x42	0.25	6.35	0.33	8.382	0.0419
Nema 14/17	35x35/42x42	0.25	6.35	0.384	9.7536	0.0488
Nema 14/17	35x35/42x42	0.25	6.35	0.5	12.7	0.0635
**	Nema 23	57x57	0.375	9.525	0.025	0.635
	Nema 23	57x57	0.375	9.525	0.05	1.27
	Nema 23	57x57	0.375	9.525	0.063	1.6002
	Nema 23	57x57	0.375	9.525	0.083	2.1082
	Nema 23	57x57	0.375	9.525	0.1	2.54
	Nema 23	57x57	0.375	9.525	0.125	3.175
	Nema 23	57x57	0.375	9.525	0.167	4.2418
	Nema 23	57x57	0.375	9.525	0.2	5.08
	Nema 23	57x57	0.375	9.525	0.25	6.35
	Nema 23	57x57	0.375	9.525	0.375	9.525
	Nema 23	57x57	0.375	9.525	0.384	9.7536
	Nema 23	57x57	0.375	9.525	0.5	12.7
	Nema 23	57x57	0.375	9.525	1.0	25.4
	Nema 34	87x87	0.625	15.875	0.1	2.54
	Nema 34	87x87	0.625	15.875	0.125	3.175
	Nema 34	87x87	0.625	15.875	0.2	5.08
	Nema 34	87x87	0.625	15.875	0.25	6.35
	Nema 34	87x87	0.625	15.875	0.5	12.7
	Nema 34	87x87	0.625	15.875	1.0	25.4

\* values truncated

**Note:** External shaft version has more options than shown in the above list. Please contact company for details. Travel per step is based on a 2 phases 1.8 ° step angle motor. The travel per step will vary with 0,9 degree, 3 phases, or 5 phases motors. \*\* Nema 17 is also available with 0.375 inch DIA screw in External Shaft only.

## SIZE 8 · 20 mm

### Hybrid Stepper Motor Linear Actuators



Available travel per step:

Motor Type	Voltage (V)	Current (A)	Resistance (Ω)	Inductance (mH)	Lead Wire No.	Motor Length (mm)
8-2030-4-050	2.5	0.5	5.0	1.2	4	30
8-2040-4-050	4.4	0.5	8.8	2.7	4	40

**For example 8-2030-4-050:** 8 = Nema 8 motor, 2030 = single stack motor, 4 = 4 lead, 050 = 0.5 A

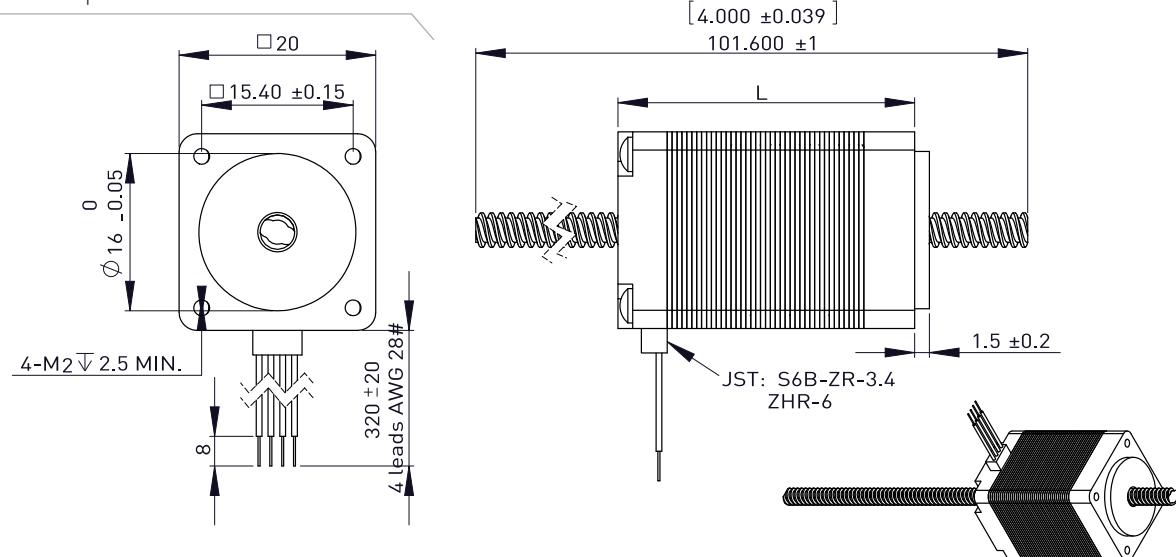
**Available Lead Screws and Travel per Step** Please consult your authorized sales representative for custom products.

Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Lead (mm)	Lead Code	Travel Per Step (mm)*
0.138	3.5052	0.024	0.6096	AA	0.003
0.138	3.5052	0.048	1.2192	B	0.0061
0.138	3.5052	0.079	2.0	G	0.01
0.138	3.5052	0.158	4.0	M	0.02
0.138	3.5052	0.315	8.0	T	0.04

\* values truncated

Dimension (mm) · Size 8 · 20 mm:

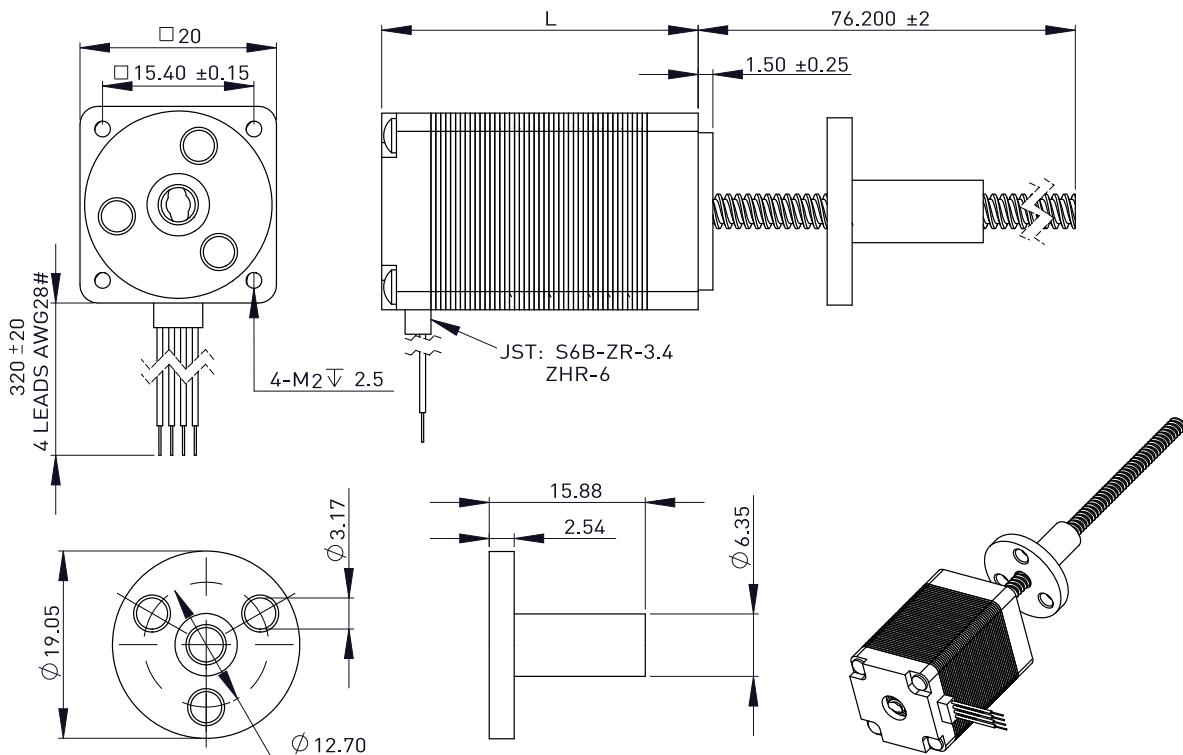
## Non Captive Motor



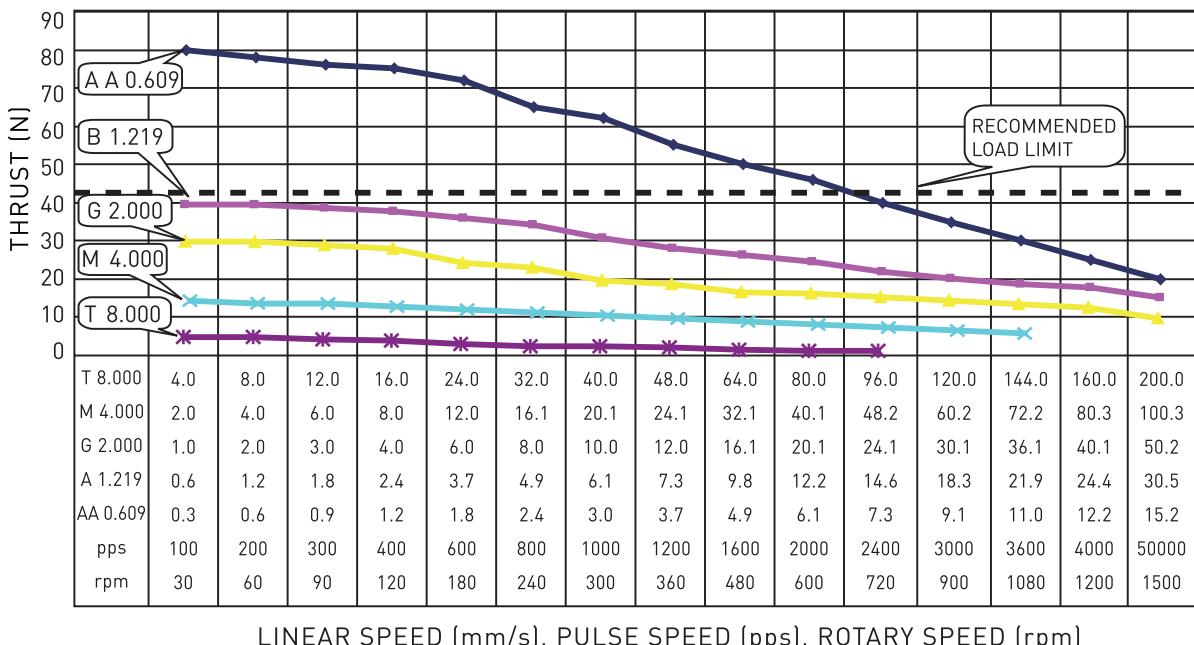
**Note: All drawings are First Angle Projection - ISO Standard**

Solid Works 3D models available

**External Shaft Motor · Size 8 · 20 mm:**



Size 8-2030-050 THRUST CURVE 40 VDC, CHOPPER DRIVER \*

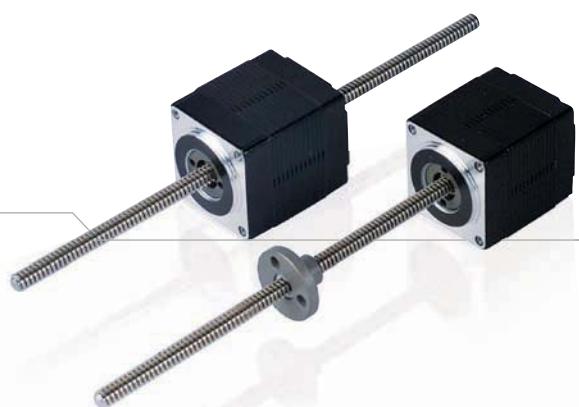


\* For performance of other motor windings, please consult your local representative.

## SIZE 11 · 28 mm

### Hybrid Stepper Motor Linear Actuators

Available travel per step from 0.003175 mm to 0.0508 mm



#### Motor Characteristics

Please consult your authorized sales representative for custom products.

Motor Type	Voltage (V)	Current (A)	Resistance (Ω)	Inductance (mH)	Lead Wire No.	Motor Length (mm)
11-2034-4-050	4.5	0.5	9.1	6.0	4	34
11-2034-4-100	2.2	1.0	2.2	1.5	4	34
11-2045-4-095	3.9	0.95	4.1	4.0	4	45

For example 11-2034-4-050: 11 = Nema 11 motor, 2034 = single stack motor, 4 = 4 lead, 050 = 0.5 A

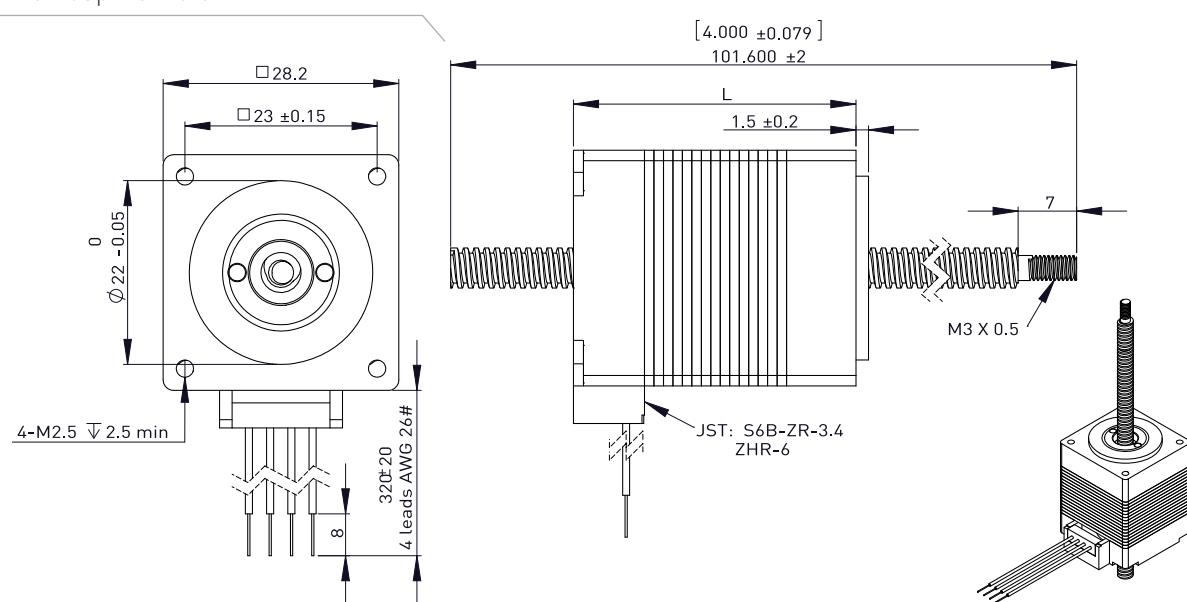
**Available Lead Screws and Travel per Step** Please consult your authorized sales representative for custom products.

Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Lead (mm)	Travel Per Step (mm)*
0.188	4.7752	0.025	0.635	0.0032
0.188	4.7752	0.05	1.27	0.0063
0.188	4.7752	0.1	2.54	0.0127
0.188	4.7752	0.2	5.08	0.0254
0.188	4.7752	0.4	10.16	0.0508

\* values truncated

#### Dimension (mm) · Size 11 · 28 mm:

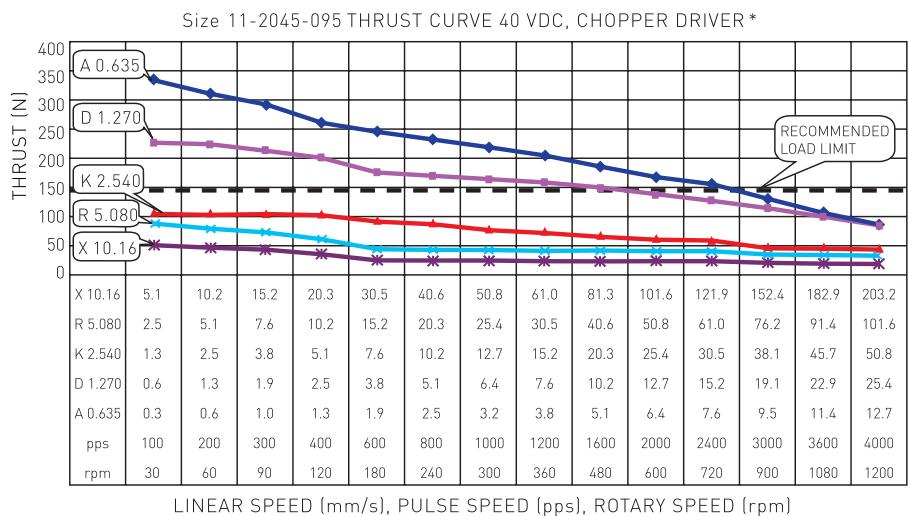
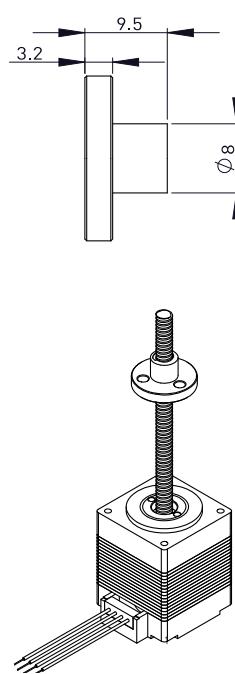
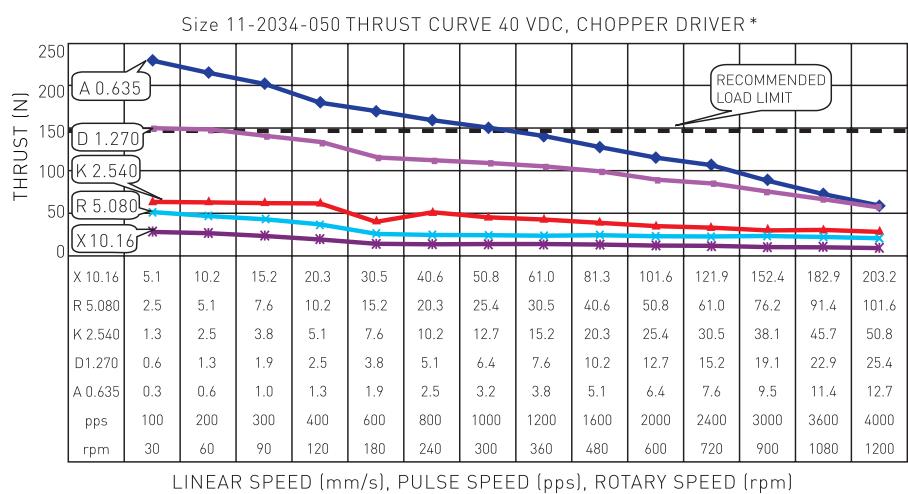
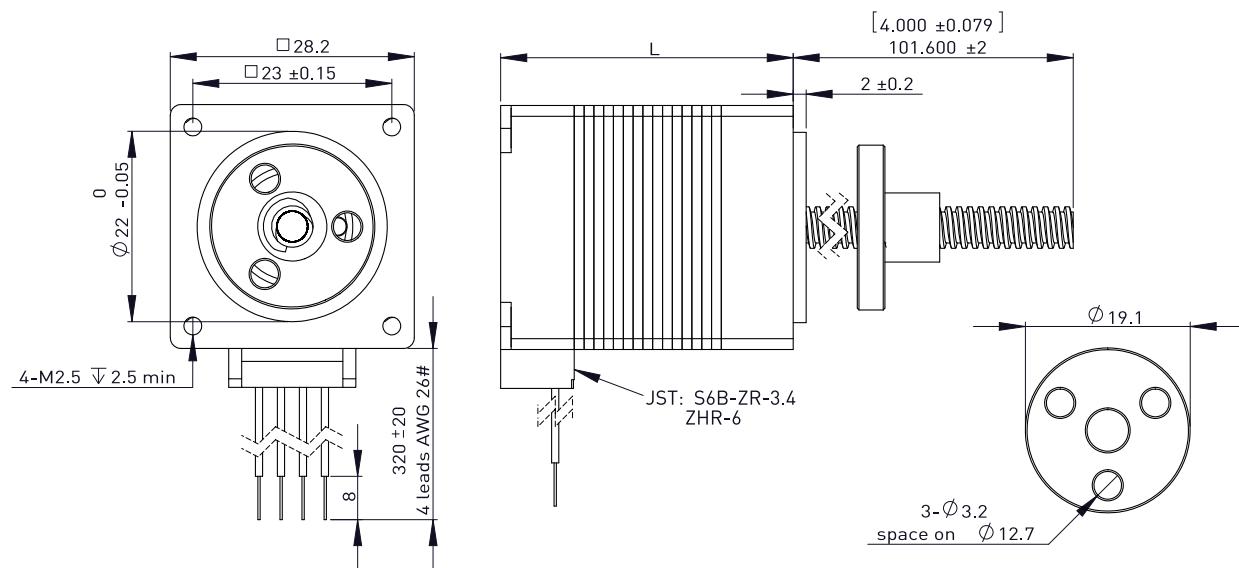
Non Captive Motor



**Note:** All drawings are First Angle Projection – ISO Standard

Solid Works 3D models available

**External Motor · Size 11 · 28 mm:**



\* For performance of other motor windings, please consult your local representative.

## SIZE 14 · 35 mm

### Hybrid Stepper Motor Linear Actuators



Available travel per step from 0.003 mm to 0.0635 mm

**Motor Characteristics** Please consult your authorized sales representative for custom products.

Motor Type	Voltage (V)	Current (A)	Resistance (Ω)	Inductance (mH)	Lead Wire No.	Motor Length (mm)
14-2035-4-050	6.6	0.5	13.2	14.0	4	35
14-2035-4-100	3.3	1.0	3.3	3.6	4	35
14-2035-4-150	2.2	1.5	1.5	1.6	4	35
14-2047-4-050	12.0	0.5	24.0	29.0	4	47
14-2047-4-100	6.0	1.0	6.0	7.2	4	47
14-2047-4-150	4.0	1.5	2.7	1.8	4	47

For example 14-2035-4-050: 14 = Nema 14 motor, 2035 = single stack motor, 4 = 4 lead motor, 050 = 0.5 A

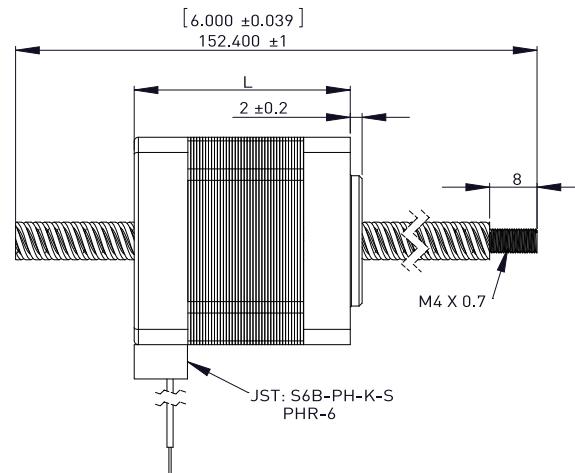
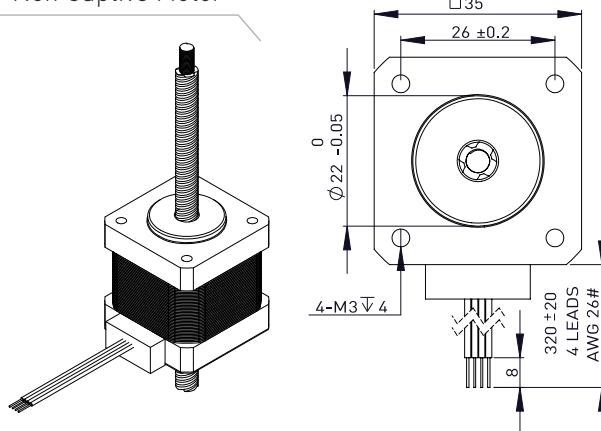
**Available Lead Screws and Travel per Step** Please consult your authorized sales representative for custom products.

Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Travel Per Step @ 1.8 deg (mm)	Travel Per Step @ 0.9 deg (mm)*
0.25	6.35	0.024	0.003	0.0015
0.25	6.35	0.048	0.006	0.003
0.25	6.35	0.05	0.006	0.0032
0.25	6.35	0.063	0.008	0.004
0.25	6.35	0.096	0.012	0.0061
0.25	6.35	0.1	0.012	0.0064
0.25	6.35	0.192	0.024	0.0122
0.25	6.35	0.25	0.031	0.0159
0.25	6.35	0.33	0.041	0.021
0.25	6.35	0.5	0.0635	0.03175

\* values truncated

#### Dimension (mm) · Size 14 · 35 mm:

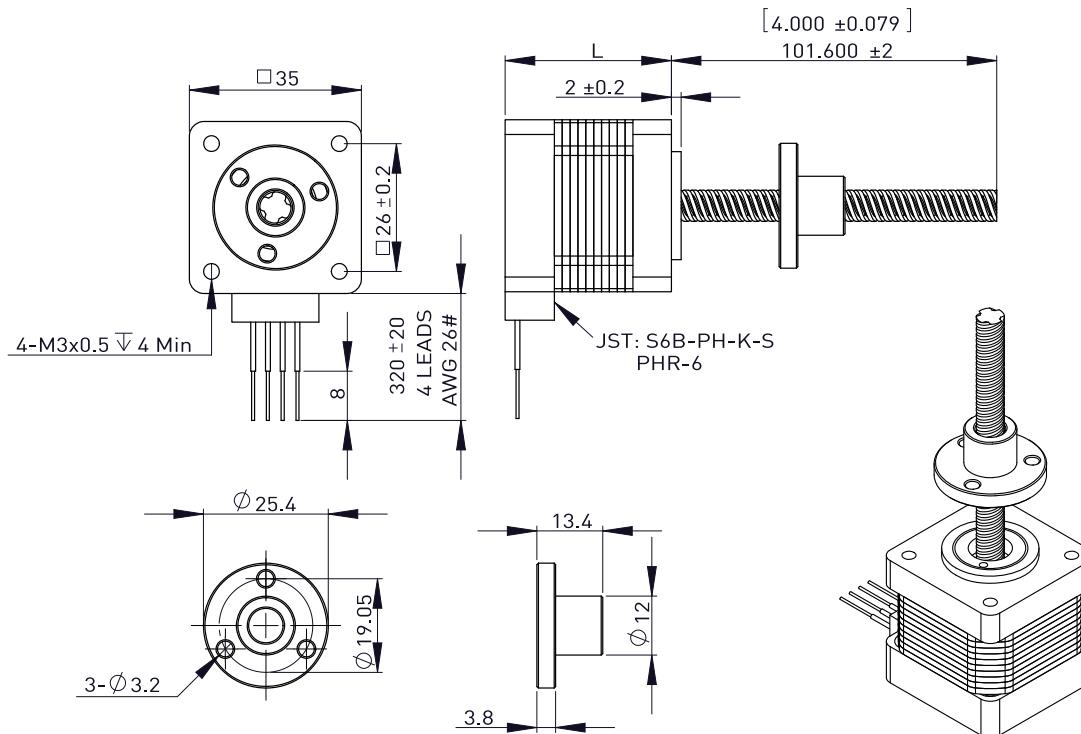
Non Captive Motor



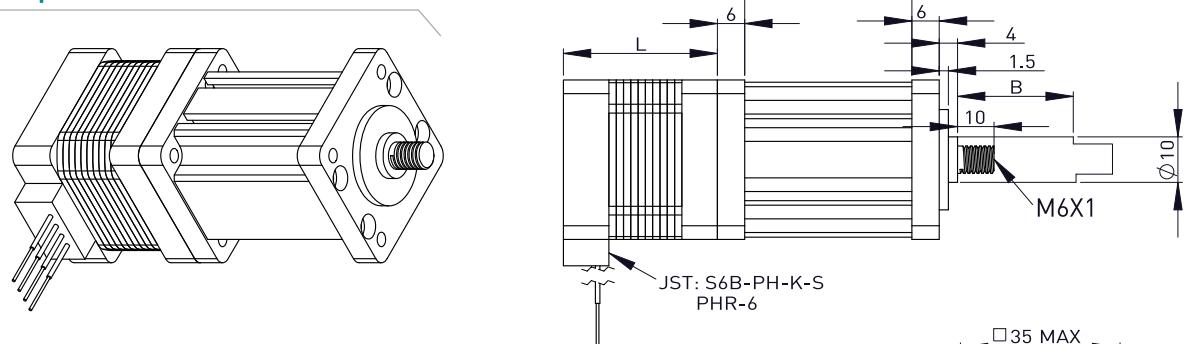
**Note:** All drawings are First Angle Projection – ISO Standard

Solid Works 3D models available

**External Motor · Size 14 · 35 mm:**

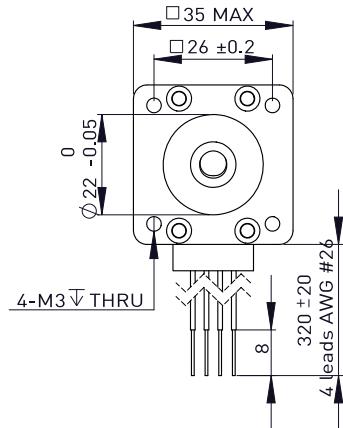


**Captive Motor · Size 14 · 35 mm:**



Please consult your authorized sales representative for custom products.

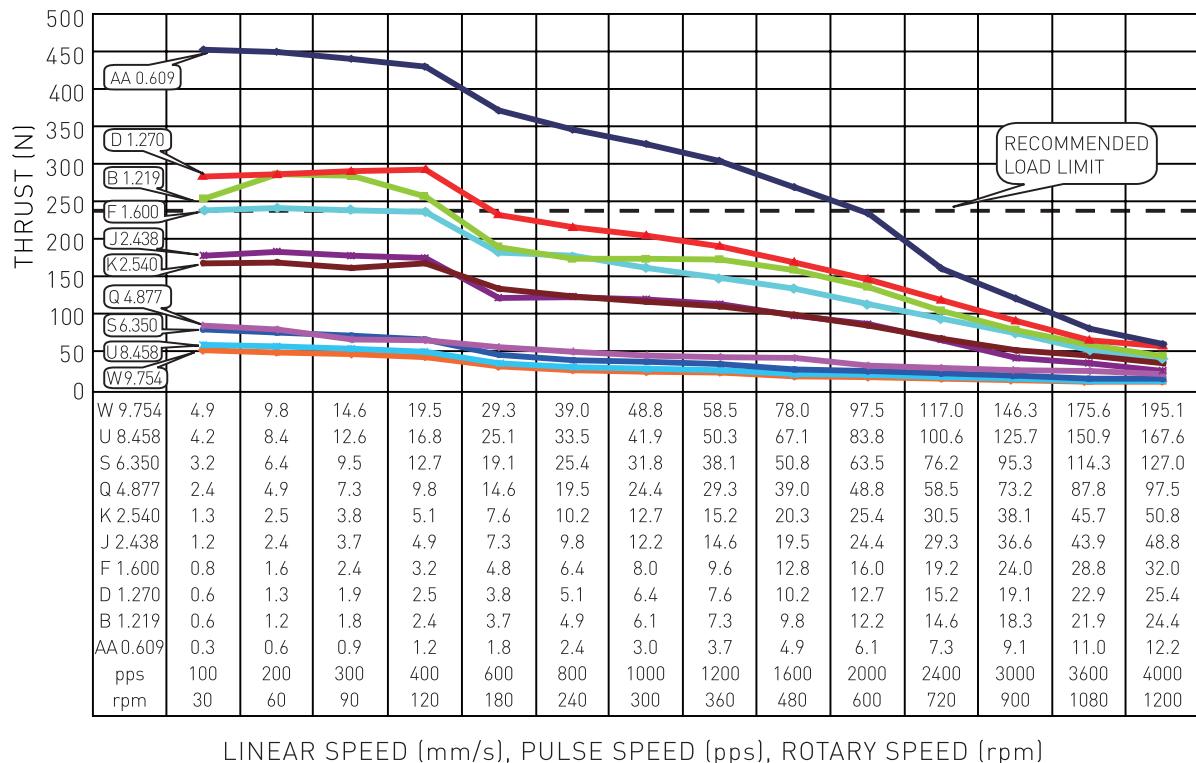
Stroke B inch (mm)	Dimension A (mm)	Dimension L (mm)
0.5 (12.7)	36.7	
0.75 (19.05)	43.05	
1.0 (25.4)	49.4	Single stack motor 35 mm
1.25 (31.8)	55.8	Double stack motor 49 mm
1.5 (38.1)	62.1	
2.0 (50.8)	74.8	
2.5 (63.5)	87.5	



**Note: All drawings are First Angle Projection – ISO Standard**

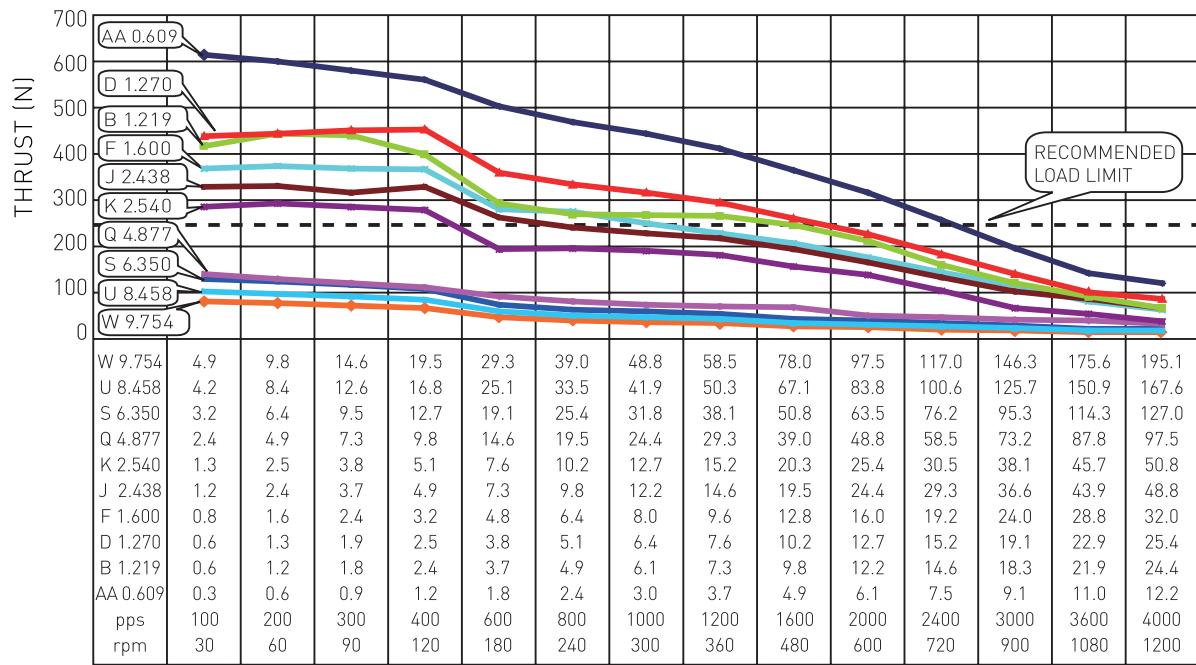
Solid Works 3D models available

Size 14-2035-050 THRUST CURVE 40 VDC, CHOPPER DRIVER \*



LINEAR SPEED (mm/s), PULSE SPEED (pps), ROTARY SPEED (rpm)

Size 14-2047-100 THRUST CURVE 40 VDC, CHOPPER DRIVER \*



LINEAR SPEED (mm/s), PULSE SPEED (pps), ROTARY SPEED (rpm)

\* For performance of other motor windings, please consult your local representative.

## SIZE 17 · 42 mm Hybrid Stepper Motor Linear Actuators



Available travel per step from 0.003 mm to 0.127 mm

**Motor Characteristics** Please consult your authorized sales representative for custom products.

Motor Type	Voltage (V)	Current (A)	Resistance (Ω)	Inductance (mH)	Lead Wire No.	Motor Length (mm)
17-2035-4-050	7.2	0.5	14.4	19.8	4	35
17-2035-4-100	3.6	1.0	3.6	5.0	4	35
17-2035-4-150	2.4	1.5	1.6	2.2	4	35
17-2049-4-050	11.0	0.5	22.0	46.0	4	49
17-2049-4-120	4.5	1.2	3.8	8.0	4	49
17-2049-4-250	2.2	2.5	0.87	1.8	4	49

For example 17-2035-4-050: 17 = Nema 17 motor, 2035 = single stack motor, 4 = 4 lead, 050 = 0.5 A

**Available Lead Screws and Travel per Step** Please consult your authorized sales representative for custom products.

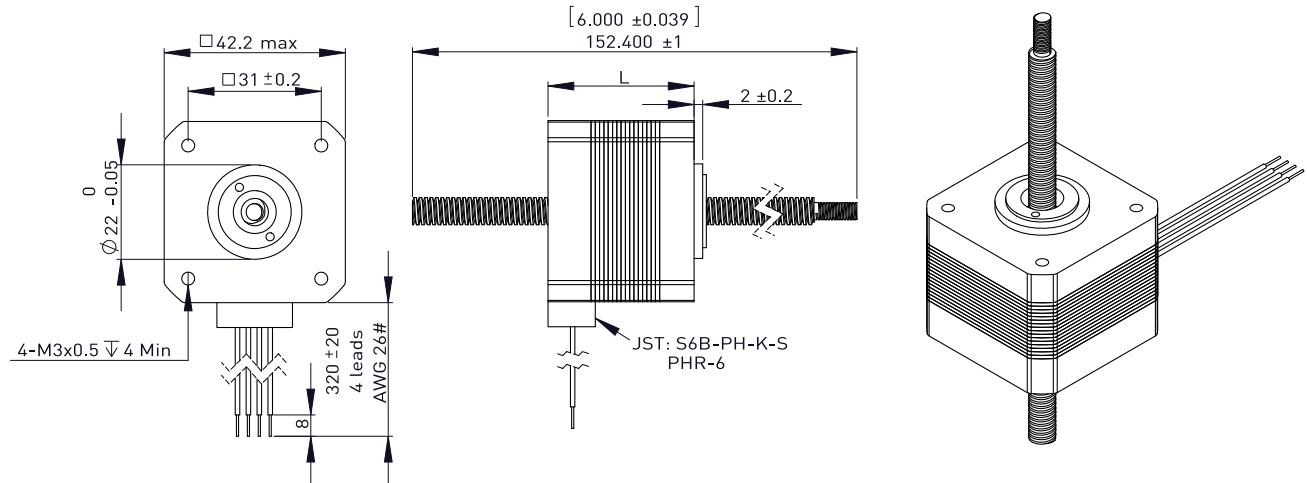
Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Lead (mm)	Travel Per Step @ 1.8 deg (mm)	Travel Per Step @ 0.9 deg (mm)*
0.25	6.35	0.024	0.6096	0.003	0.0015
0.25	6.35	0.048	1.2192	0.006	0.003
0.25	6.35	0.05	1.27	0.006	0.0032
0.25	6.35	0.063	1.6002	0.008	0.004
0.25	6.35	0.096	2.4384	0.012	0.0061
0.25	6.35	0.1	2.54	0.012	0.0064
0.25	6.35	0.192	4.8768	0.024	0.0122
0.25	6.35	0.25	6.35	0.031	0.0159
0.25	6.35	0.33	8.382	0.041	0.021
0.25	6.35	0.384	9.7536	0.048	0.0244
0.25	6.35	0.5	12.7	0.0635	0.03175
0.375	9.525	0.025	0.635	0.003	0.0016
0.375	9.525	0.05	1.27	0.006	0.0032
0.375	9.525	0.063	1.6002	0.008	0.004
0.375	9.525	0.083	2.1082	0.01	0.0053
0.375	9.525	0.1	2.54	0.012	0.0064
0.375	9.525	0.125	3.175	0.015	0.0079
0.375	9.525	0.167	4.2418	0.021	0.0106
0.375	9.525	0.2	5.08	0.025	0.0127
0.375	9.525	0.25	6.35	0.031	0.0159
0.375	9.525	0.375	9.525	0.047	0.0238
0.375	9.525	0.384	9.7536	0.048	0.0244
0.375	9.525	0.5	12.7	0.063	0.0318
0.375	9.525	1.0	25.4	0.127	0.0635

**Note:** 0.375 DIA shaft only available with external shaft

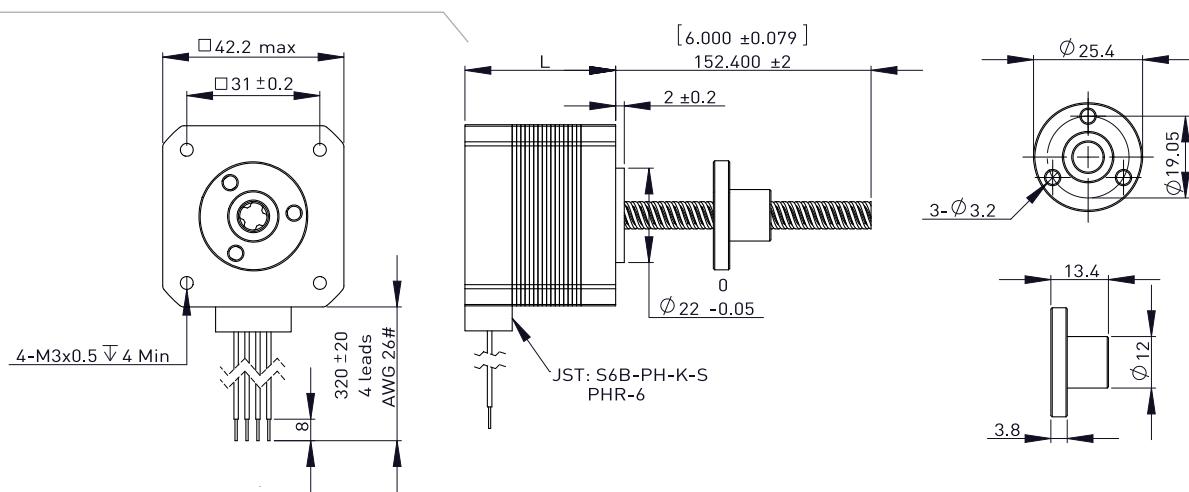
\* values truncated

### Dimension (mm) - Size 17 · 42 mm:

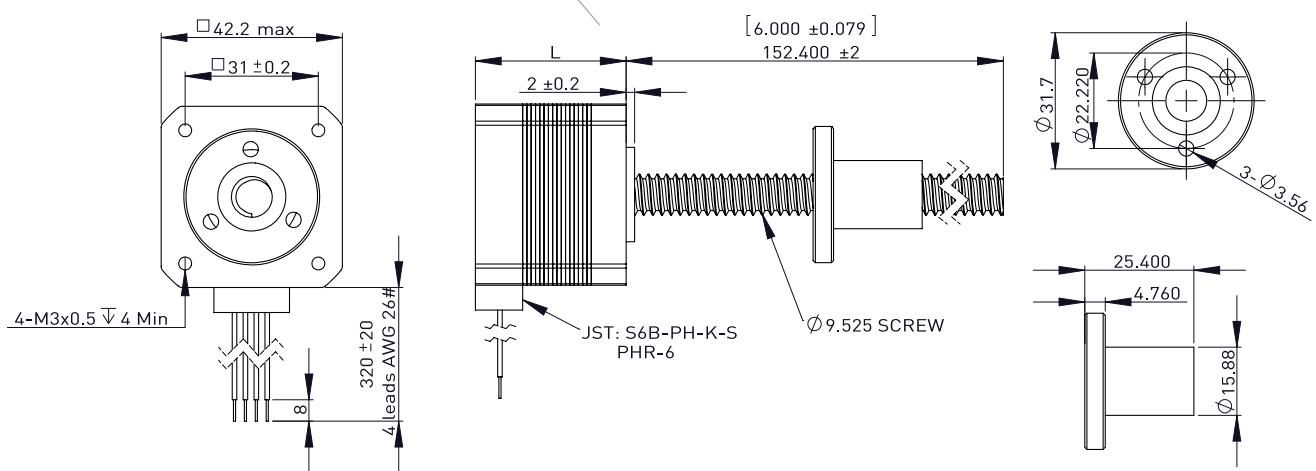
Non Captive Motor



### External Motor · Size 17 · 42 mm:



### Dia. 9.525 mm Lead Screw · Size 17 · 42 mm:



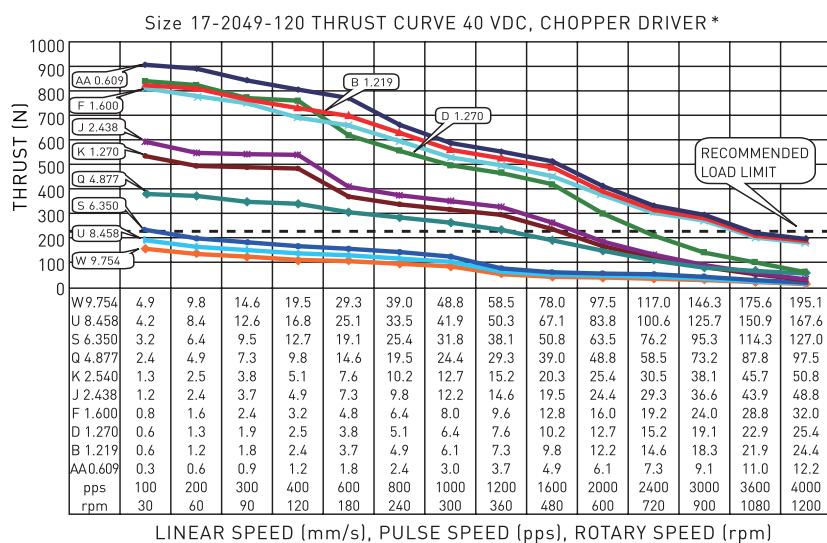
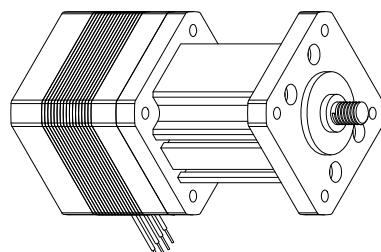
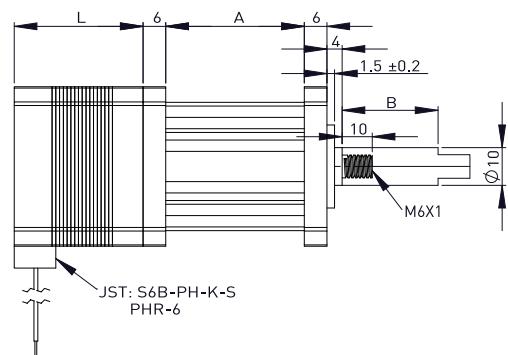
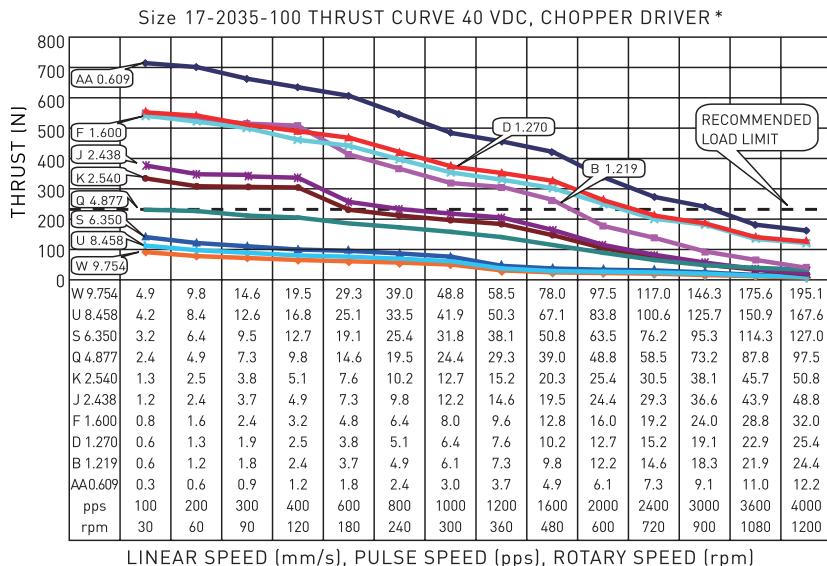
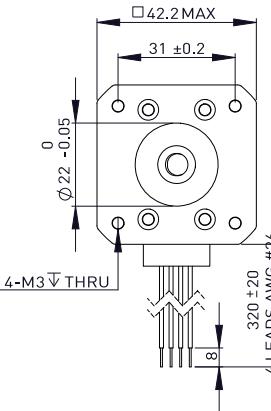
Note: All drawings are First Angle Projection - ISO Standard

Solid Works 3D models available

**Captive Motor · Size 17 · 42 mm:**

Please consult your authorized sales representative for custom products.

Stroke B inch (mm)	Dimension A (mm)	Dimension L (mm)
0.5 (12.7)	36.7	
0.75 (19.05)	43.05	
1.0 (25.4)	49.4	
1.25 (31.8)	55.8	
1.5 (38.1)	62.1	
2.0 (50.8)	74.8	
2.5 (63.5)	87.5	

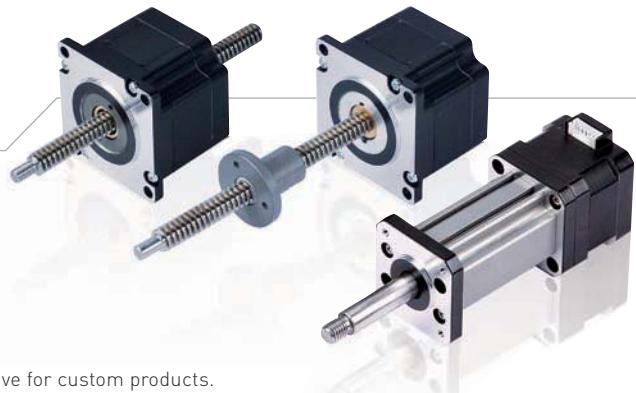


\* For performance of other motor windings, please consult your local representative.

## SIZE 23 · 57 mm

### Hybrid Stepper Motor Linear Actuators

Available travel per step from 0.0016 mm to 0.127 mm,  
max. thrust force is up to 800 N.



**Motor Characteristics** Please consult your authorized sales representative for custom products.

Motor Type	Voltage (V)	Current (A)	Resistance (Ω)	Inductance (mH)	Lead Wire No.	Motor Length (mm)
23-2047-4-100	6.4	1.0	6.4	16.4	4	47
23-2047-4-200	3.2	2.0	1.6	4.1	4	47
23-2047-4-300	2.1	3.0	0.7	1.7	4	47
23-2066-4-100	10.8	1.0	10.8	32.0	4	66
23-2066-4-250	4.2	2.5	1.7	5.2	4	66
23-2066-4-400	2.4	4.0	0.65	2.0	4	66

**For example 23-2047-4-100:** 23 = Nema 23 motor, 2047 = single stack motor, 4 = 4 lead motor, 100 = 1.0 A

**Available Lead Screws and Travel per Step** Please consult your authorized sales representative for custom products.

Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Lead (mm)	Travel Per Step @ 1.8 deg (mm)	Travel Per Step @ 0.9 deg (mm)*
0.375	9.525	0.025	0.635	0.003	0.0016
0.375	9.525	0.05	1.27	0.006	0.0032
0.375	9.525	0.063	1.6002	0.008	0.004
0.375	9.525	0.083	2.1082	0.01	0.0053
0.375	9.525	0.1	2.54	0.012	0.0064
0.375	9.525	0.125	3.175	0.015	0.0079
0.375	9.525	0.167	4.2418	0.021	0.0106
0.375	9.525	0.2	5.08	0.025	0.0127
0.375	9.525	0.25	6.35	0.031	0.0159
0.375	9.525	0.375	9.525	0.047	0.0238
0.375	9.525	0.384	9.7536	0.048	0.0244
0.375	9.525	0.5	12.7	0.063	0.0318
0.375	9.525	1.0	25.4	0.127	0.0635
0.625	15.875	0.1	2.54	0.012	0.006
0.625	15.875	0.125	3.175	0.015	0.0075
0.625	15.875	0.2	5.08	0.025	0.0125
0.625	15.875	0.25	6.35	0.031	0.0155
0.625	15.875	1.0	25.4	0.127	0.0635

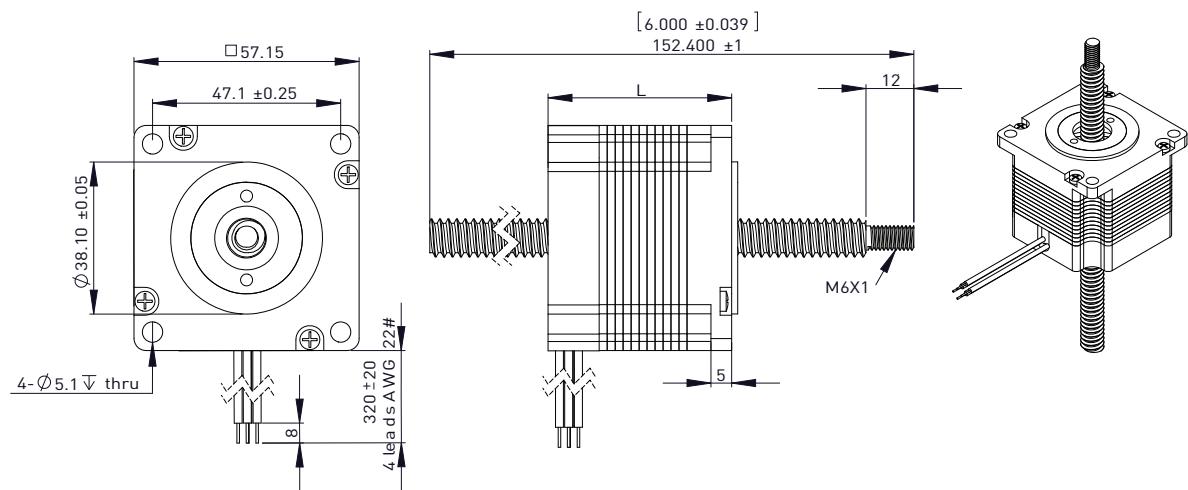
**Note:** All above screws can be used on external drive style.  
Non captive style can only select dia. 9.525 mm screws.  
15.875 DIA screws only for External shafts.

\* values truncated

**Note: All drawings are First Angle Projection – ISO Standard**

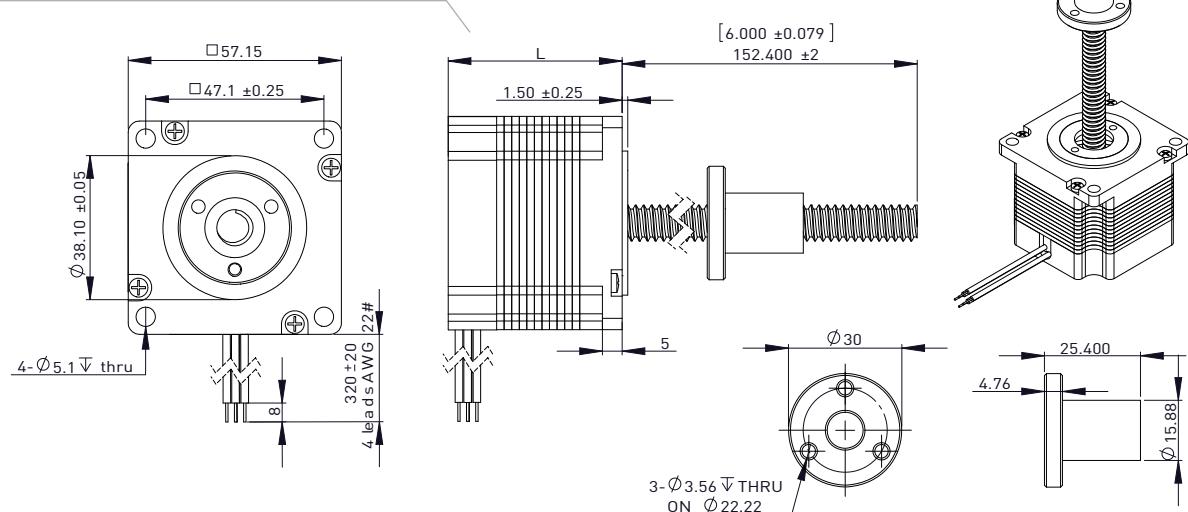
Solid Works 3D models available

**Dimension (mm) · Size 23 · 57 mm:**

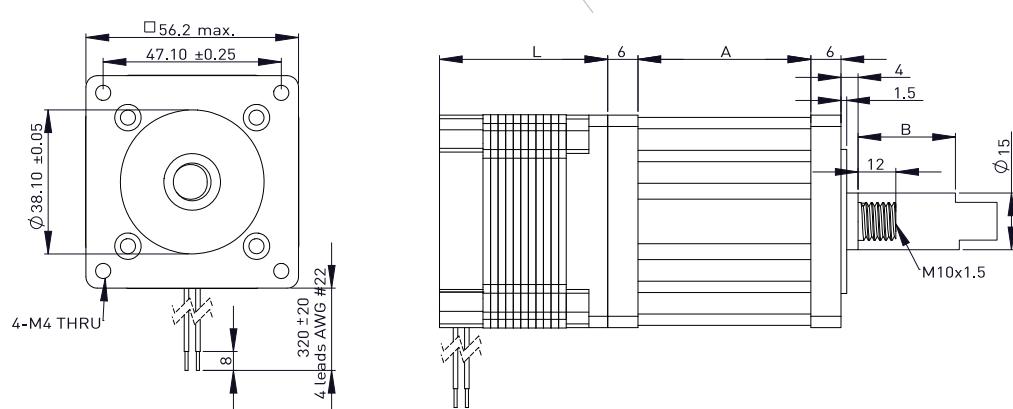


**External Motor · Size 23 · 57 mm:**

Dia. 9.525 mm Lead Screw



**Captive Motor · Size 23 · 57 mm:**



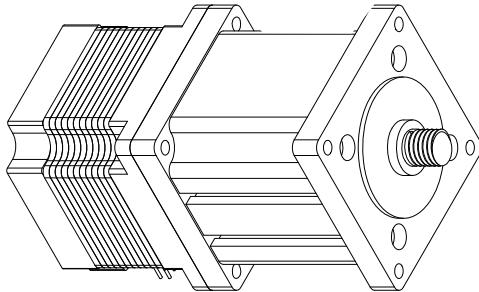
**Note: All drawings are First Angle Projection – ISO Standard**

Solid Works 3D models available

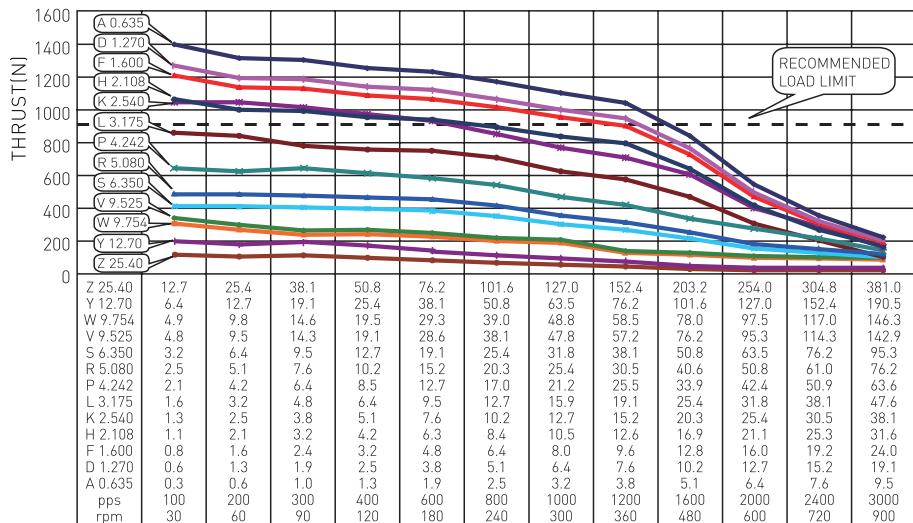
## Captive Motor - Size 23 - 57 mm:

Please consult your authorized sales representative for custom products.

Stroke B inch (mm)	Dimension A (mm)	Dimension L (mm)
0.5 (12.7)	45.7	
0.75 (19.05)	52.05	
1.0 (25.4)	58.4	
1.25 (31.8)	64.8	
1.5 (38.1)	71.1	
2.0 (50.8)	83.8	
2.5 (63.5)	96.5	

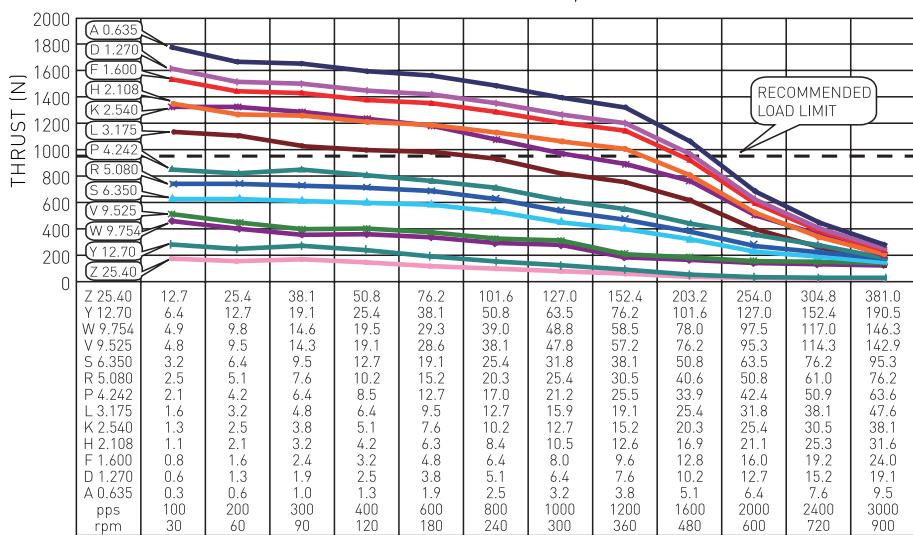


Size 23-2047-100 THRUST CURVE 40 VDC, CHOPPER DRIVER \*



LINEAR SPEED (mm/s), PULSE SPEED (pps), ROTARY SPEED (rpm)

Size 23-2066-250 THRUST CURVE 40 VDC, CHOPPER DRIVER \*



LINEAR SPEED (mm/s), PULSE SPEED (pps), ROTARY SPEED (rpm)

\* For performance of other motor windings, please consult your local representative.

## SIZE 34 · 86 mm Hybrid Stepper Motor Linear Actuators

Available travel per step from 0.00508 mm to 0.127 mm



**Motor Characteristics** Please consult your authorized sales representative for custom products.

Motor Type	Voltage (V)	Current (A)	Resistance (Ω)	Inductance (mH)	Lead Wire No.	Motor Length (mm)
34-2080-4-130	12.0	1.3	9.2	71.0	4	80
34-2080-4-300	5.1	3.0	1.7	15.0	4	80
34-2080-4-550	2.85	5.5	0.52	4.5	4	80

**For example 34-2080-4-130:** 34 = Nema 34 motor, 2080 = single stack motor, 4 = 4 lead, 130 = 1.3 A

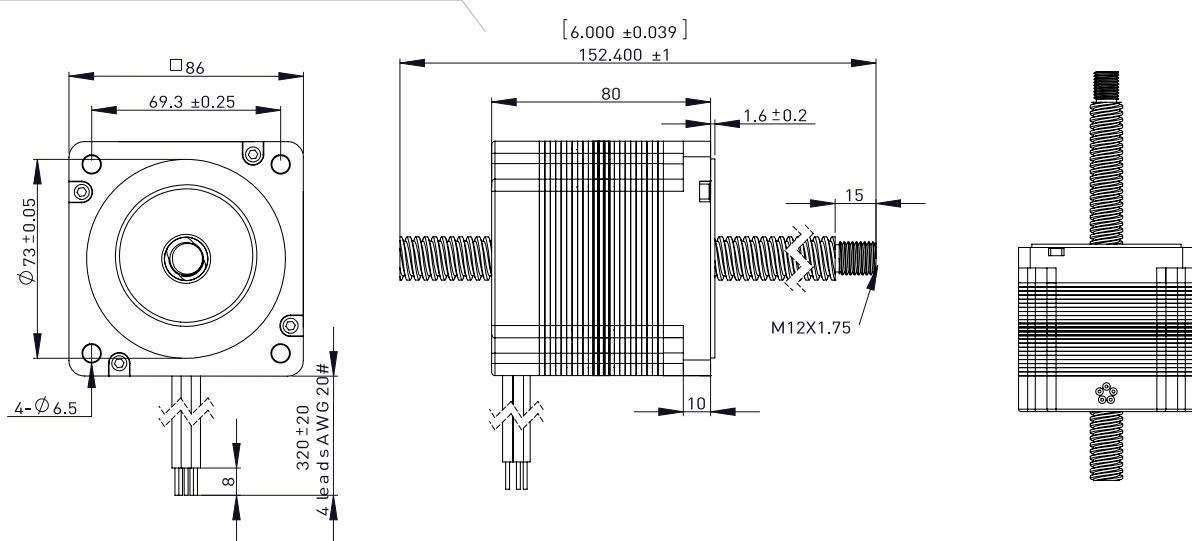
**Available Lead Screws and Travel per Step** Please consult your authorized sales representative for custom products.

Screw Dia. (inch)	Screw Dia. (mm)	Lead (inch)	Lead (mm)	Travel Per Step @ 1.8 deg (mm)	Travel Per Step @ 0.9 deg (mm)*
0.625	15.875	0.1	2.54	0.012	0.0051
0.625	15.875	0.125	3.175	0.015	0.0064
0.625	15.875	0.2	5.08	0.025	0.0102
0.625	15.875	0.25	6.35	0.031	0.0127
0.625	15.875	0.5	12.7	0.0635	0.03175
0.625	15.875	1.0	25.4	0.127	0.0508

\* values truncated

### Dimension (mm) · Size 34 · 86 mm:

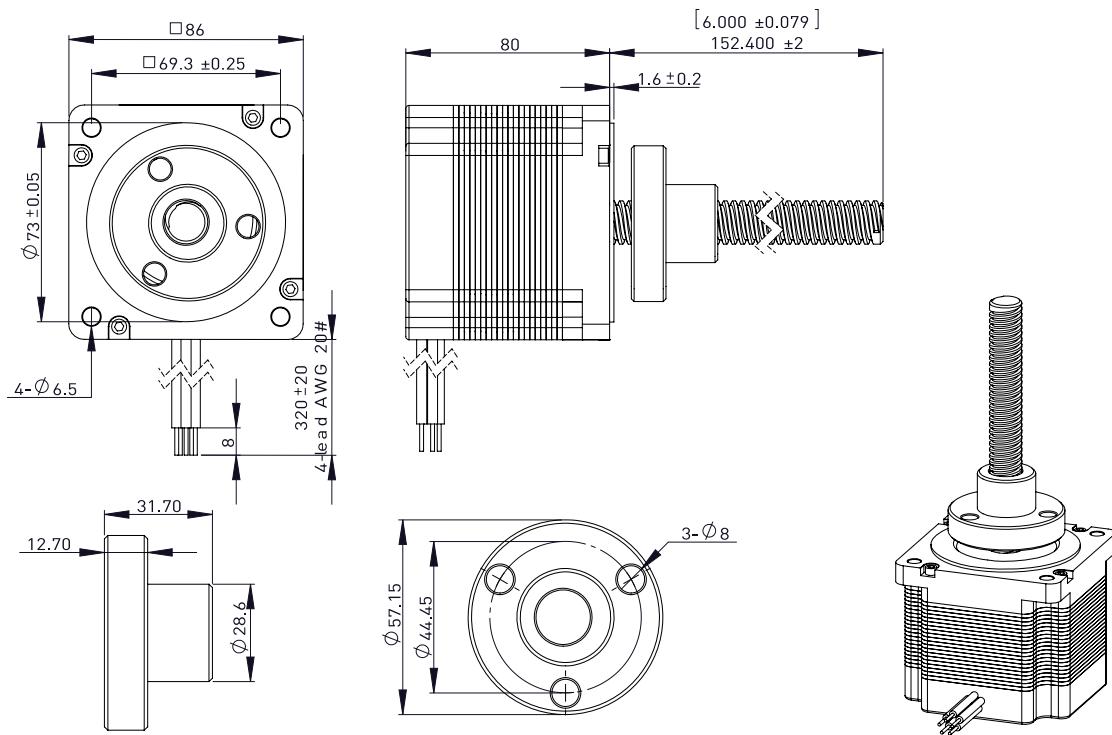
Non Captive Motor



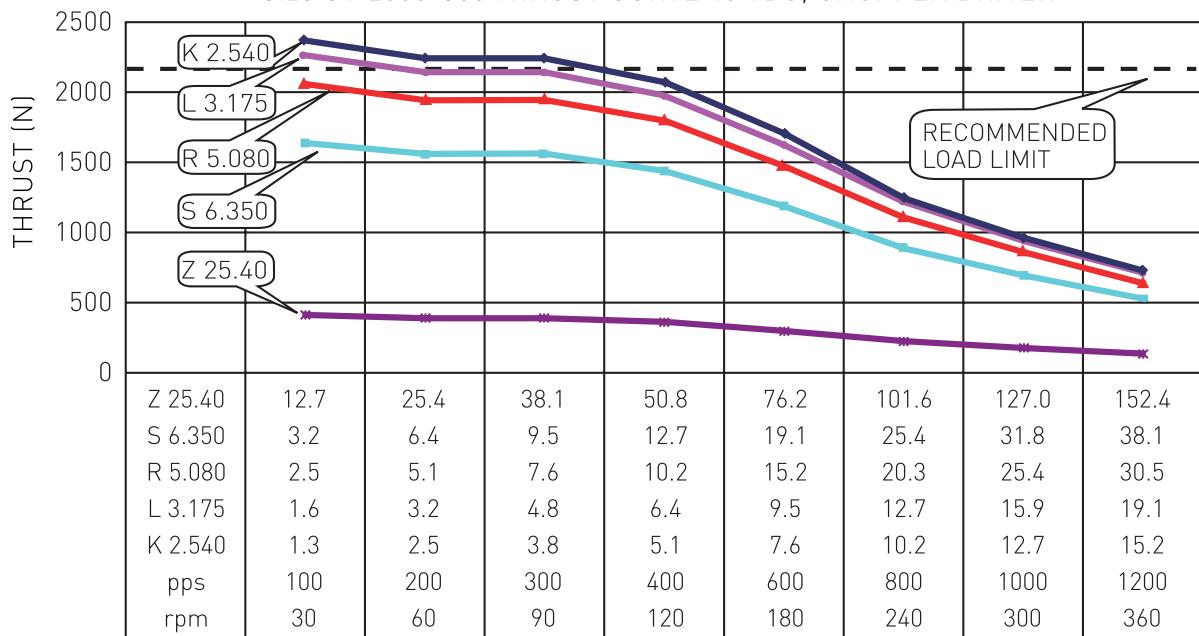
**Note: All drawings are First Angle Projection – ISO Standard**

Solid Works 3D models available

## External Motor · Size 34 · 86 mm:



Size 34-2080-300 THRUST CURVE 48 VDC, CHOPPER DRIVER \*



LINEAR SPEED (mm/s), PULSE SPEED (pps), ROTARY SPEED (rpm)

\* For performance of other motor windings, please consult your local representative.

## Lead Screw only Specification

### LSGR-6K-0150-N-001

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨

- ① L = Leadscrew Assembly
- ② Nut Style (Only for External Linear Version)
  - S = Leadscrew only (Non-Captive and Captive versions)
  - N = Standard free-wheeling nut
  - A = Antibacklash nut
- ③ Lubrication
  - G = standard grease
  - S = Leadscrew without grease
  - T = Teflon coated screw
- ④ Direction of Thread
  - R = Right hand thread
  - L = Left hand thread
  - B = Right and Left (Non-Captive version only)
  - C = Custom
- ⑤ Lead Screw Diameter
  - 3 = 3.505 mm (Nema Size 8 motor)
  - 4 = 4.775 mm (Nema Size 11 motor)
  - 6 = 6.350 mm (Nema Size 14 and 17 motor)
  - 7 = 9.525 mm (Nema Size 17 motor)
  - 9 = 9.525 mm (Nema Size 23 motor)
  - 15 = 15.875 mm (Nema Size 34 motor)
- ⑥ Lead Code (Travel per Rev and Full Step)
  - Reference motor lead screw code schedule (page 13)
- ⑦ Lead Screw Length
  - 0 150 = 150 mm
- ⑧ End Machining Option (Customs available)
  - A = Metric (see page 12)
  - B = UNC (see page 12)
  - S = Smooth (see page 12)
  - N = None
- ⑨ Reserved for custom version (001 is default)

**Screw End Machining** Reference Page 12 for options

**Note: Unless specified differently all screws are as follows:**

1. Right hand screw threads
2. Standard lubrication on leadscrew
3. No teflon coating

**Custom Leadscrew and Motor specifications welcome**



## GLOSSARY

<b>ACCURACY</b>	The difference between the actual distance travelled versus the theoretical distance travelled based on the lead
<b>AXIAL LOAD</b>	A load that is exerted at the center line of the screw
<b>BACKDRIVING</b>	Freewheeling of the nut an screw as a result of the load pushing axially on the screw
<b>BACKLASH</b>	The relative axial movement between the screw and nut
<b>CHOPPER DRIVE</b>	A constant current drive is usually bipolar. The chopper drive gets its name from the technique of rapidly switching the power on and off to control motor current. A chopper drive allows a step motor to maintain greater torque of force at higher speeds.
<b>COLUMN STRENGTH</b>	The ability of a screw to withstand a load in compression
<b>CRITICAL SPEED</b>	The rotational speed of the screw at which the first harmonic of resonance is reached
<b>DRAG TORQUE</b>	The amount of torque to overcome the friction of a system
<b>DYNAMIC LOAD</b>	Load applied to the screw while in motion
<b>EFFICIENCY</b>	The ability of a mechanical system to translate an input to an equal output
<b>FIXITY (END)</b>	The method by which the ends of the screw secured or supported
<b>LEAD</b>	The linear travel at one revolution of the screw
<b>LEFT HAND THREAD</b>	Counter clockwise rotation
<b>PITCH</b>	The axial distance between threads
<b>RADIAL LOAD</b>	A load exerted at 90 degrees or perpendicular to a screw
<b>REPEATABILITY</b>	The capability of a screw and nut system to reach the same commanded position continuously
<b>RESOLUTION</b>	Incremental linear distance the actuator's (motor) output shaft will move per input pulse
<b>RESONANCE</b>	Vibration occurring when a system is a mechanical system is in an unstable range
<b>RIGHT HAND THREAD</b>	Clockwise rotation
<b>SIDELOADING</b>	Same as a radial load (very undesirable)
<b>STATIC LOAD</b>	Load applied to the screw at standstill
<b>STRAIGHTNESS</b>	Linear uniformity of a screw
<b>TOTAL INDICATED RUNOUT</b>	A measurement of the amount of straightness of a screw
<b>TRAVEL PER STEP</b>	Linear translation of one full step of the motor

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