

## I2C Bus Functions

The I2C Functions are intended for easy interfacing between C programs and various peripherals using the Philips I2C bus.

These functions treat the microcontroller as a bus master and the peripherals as slaves.

The prototypes for these functions are placed in the file **i2c.h**, located in the `..\INC` subdirectory. This file must be [#include](#) -ed before using the functions.

Prior to `#include` -ing the **i2c.h** file, you must declare which microcontroller port and port bits are used for communication through the I2C bus.

Example:

```
/* the I2C bus is connected to PORTB */
/* the SDA signal is bit 3 */
/* the SCL signal is bit 4 */
#asm
    .equ __i2c_port=0x18
    .equ __sda_bit=3
    .equ __scl_bit=4
#endasm

/* now you can include the I2C Functions */
#include <i2c.h>
```

The I2C Functions are:

### **void i2c\_init(void)**

this function initializes the I2C bus.

This is the first function that must be called prior to using the other I2C Functions.

### **unsigned char i2c\_start(void)**

issues a START condition.

Returns 1 if bus is free or 0 if the I2C bus is busy.

### **void i2c\_stop(void)**

issues a STOP condition.

### **unsigned char i2c\_read(unsigned char ack)**

reads a byte from the bus.

The **ack** parameter specifies if an acknowledgement is to be issued after the byte was read.

Set **ack** to 0 for no acknowledgement or 1 for acknowledgement.

### **unsigned char i2c\_write(unsigned char data)**

writes the byte data to the bus.

Returns 1 if the slave acknowledges or 0 if not.

Example how to access an Atmel 24C02 256 byte I2C EEPROM:

```
/* the I2C bus is connected to PORTB */
/* the SDA signal is bit 3 */
/* the SCL signal is bit 4 */
#asm
    .equ __i2c_port=0x18
    .equ __sda_bit=3
    .equ __scl_bit=4
#endasm
```

```

/* now you can include the I2C Functions */
#include <i2c.h>

/* function declaration for delay_ms */
#include <delay.h>

#define EEPROM_BUS_ADDRESS 0xa0

/* read a byte from the EEPROM */
unsigned char eeprom_read(unsigned char address) {
unsigned char data;
i2c_start();
i2c_write(EEPROM_BUS_ADDRESS);
i2c_write(address);
i2c_start();
i2c_write(EEPROM_BUS_ADDRESS | 1);
data=i2c_read(0);
i2c_stop();
return data;
}

/* write a byte to the EEPROM */
void eeprom_write(unsigned char address, unsigned char data) {
i2c_start();
i2c_write(EEPROM_BUS_ADDRESS);
i2c_write(address);
i2c_write(data);
i2c_stop();

/* 10ms delay to complete the write operation */
delay_ms(10);
}

void main(void) {
unsigned char i;

/* initialize the I2C bus */
i2c_init();

/* write the byte 55h at address AAh */
eeprom_write(0xaa,0x55);

/* read the byte from address AAh */
i=eeprom_read(0xaa);

while (1); /* loop forever */
}

```