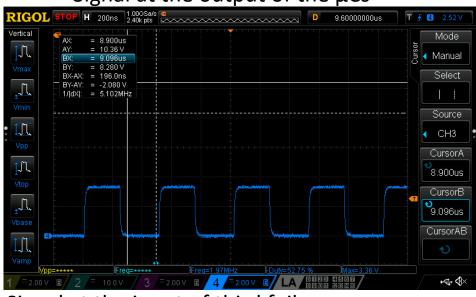
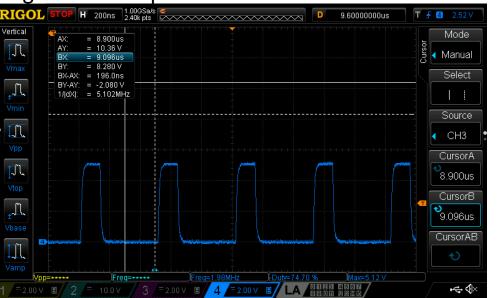
## Clock Signal by 4 cascaded SPI-foils @2MHz

Signal at the output of the μCs

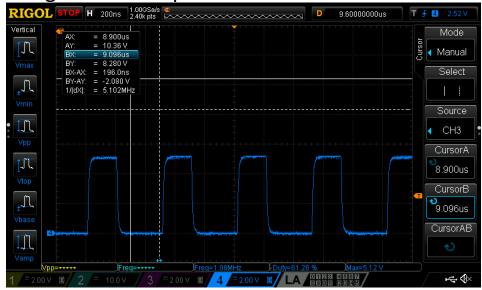


P.S. the fourth is working Only at ¾ of the foil

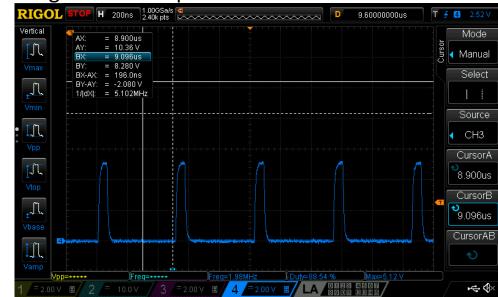
Signal at the input of third foil



Signal at the input of second foil

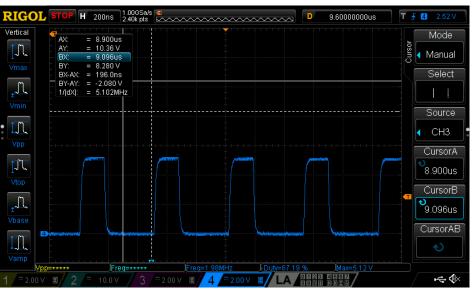


Signal at the input of 4 foils

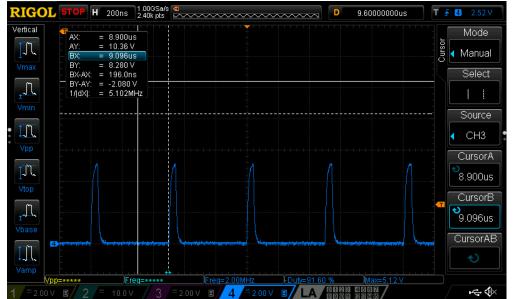


# Clock Signal by 4 cascaded SPI-foils @2MHz

#### Signal in the middler of the second foil



Signal in the middler of the fourth foil



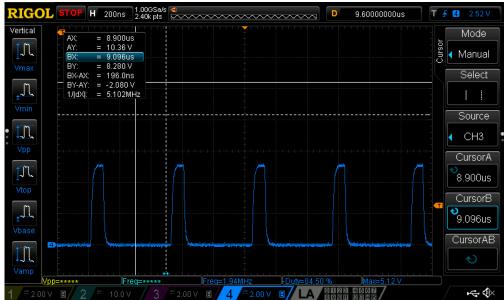
P.S. the duty cycle between Third Foils middle and the ¾ of the Third foil is 5%

⇒ High delay between LED
Causing signal distortion
As the number of LED
increase

Signal in the middle of third foil

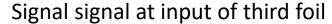


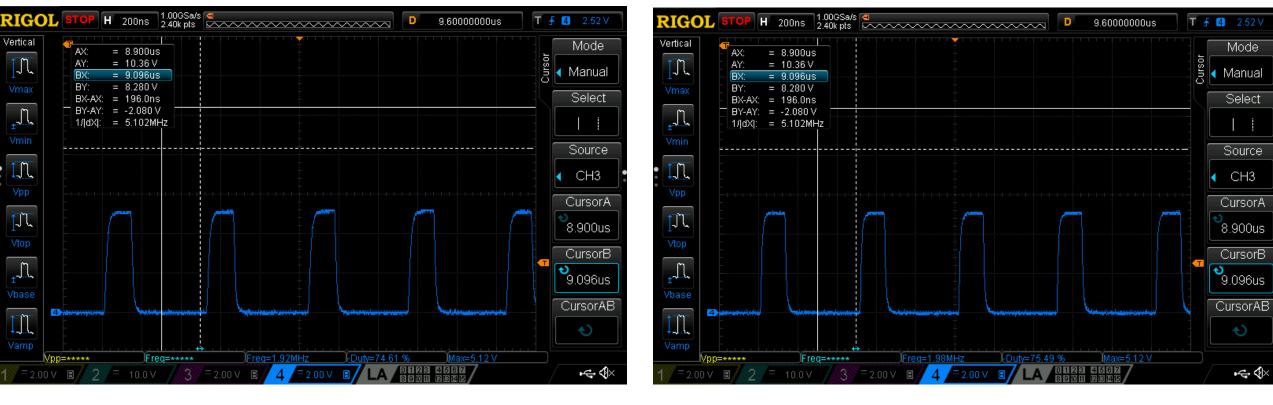
Signal at about ¾ of the third foils



# Clock Signal by 4 cascaded SPI-foils @2MHz

Signal at output of second foil

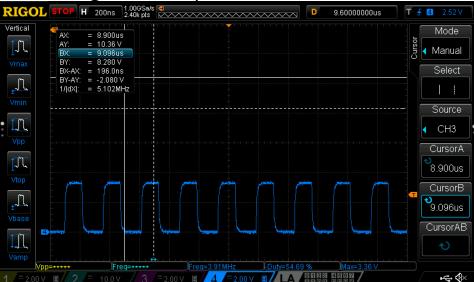




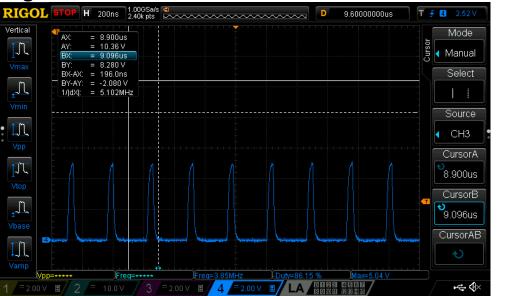
=> No considerable delay between foils

## Clock Signal by 4 cascaded SPI-foils @4MHz

Signal at output of the microcontroller



Signal in the middler of the second foil



P.S. The second foil is working At  $\frac{3}{4}$ .

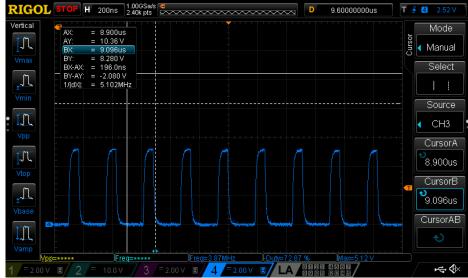
Signal distortion as the Data rate increase.

⇒ The duty cycle keep on Reducing.

They are no further circuit Between two LEDs.

The voltage quality is stable And no high ripple

Signal at input of the second foil



Signal at ¾ of the second foil

